CHARACTERIZATION AND DERIVATION OF HEARD-OF PREDICATES FOR ASYNCHRONOUS MESSAGE-PASSING MODELS

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Abstract. In distributed computing, multiple processes interact to solve a problem together. The main model of interaction is the message-passing model, where processes communicate by exchanging messages. Nevertheless, there are several models varying along important dimensions: degree of synchrony, kinds of faults, number of faults... This variety is compounded by the lack of a general formalism in which to abstract these models, for translating results from one to the other. One way to bring order to these models is to constrain them further, to communicate in rounds. This is the setting of the Heard-Of model, which captures many models through predicates on the messages sent in a round and received on time (at this round or before, where the round is the one of the receiver). Yet, it is not easy to define the predicate that best captures a given operational model. The question is even harder for the asynchronous case, as unbounded message delay means the implementation of rounds must depend on details of the model.

This paper shows that characterising asynchronous models by heard-of predicates is indeed meaningful. This characterization relies on the introduction of delivered predicates, an intermediate abstraction between the informal operational model and the heard-of predicates. Our approach splits the problem into two steps: first extract the delivered model capturing the informal model, and then characterize the heard-of predicates that can be generated by this delivered model. For the first part, we provide examples of delivered predicates, and an approach to derive more. It uses the intuition that complex models are a composition of simpler models. We thus define operations like union, succession or repetition that make it easier to derive complex delivered predicates from simple ones while retaining expressivity. For the second part, we formalize and study strategies for when to change rounds. Intuitively, the characterizing predicate of a model is the one generated by a strategy that waits for as much messages as possible, without blocking forever.

1. Introduction

1.1. Motivation. Distributed computing studies how multiple processes can accomplish computational tasks by interacting with each other. Various means of communication are traditionally studied; we focus here on message-passing, where processes exchange messages. Yet, message-passing models still abound: they might have various degrees of synchrony (how much processes can drift from each other in term of processing speed or communication), different kinds of faults (processes crashing, processes crashing and restarting, message loss,
message corruption...), different network topologies... Although some of these differences are quantitative, such as the number of faults, others are qualitative, like the kinds of faults. This in turn means that abstracting most message-passing models into one formal framework proves difficult. Indeed, most works in the literature limit themselves to either a narrow subset of such models that can easily be abstracted together, or consider a handful of models one by one. Hence it is difficult to compare, organize and extend results from the literature to other message-passing models. Formal verification is also made significantly harder by the need to derive a formal version of each model.

One step towards unifying a broad range of message-passing models is to abstract them through the messages which will be received. A crashed process would thus be considered as a silent process, for example. Yet this information — which messages can be received — is hard to capture in a simple mathematical object. This is one reason why these proposals further constrain communication to explicitly use rounds: each process repeatedly broadcasts a message with its current round number, waits for some messages bearing this round number, and changes round by computing its next state and its next message. The distributed algorithm tells each process how to change its state at the end of each round, and which message to broadcast in the next round. Then the model can be abstracted through which message will be received by which process at each round, and each such possibility is represented either through a function or a sequence of graphs. At first glance, forcing rounds onto these models might seem like a strong constraint, severely limiting the generality of this unification. But rounds are actually ubiquitous in distributed computing: they are present in the complexity analyses of synchronous message-passing models, in the fault-tolerant algorithms for asynchronous models, in the algorithms using failure-detectors... Since the use of rounds for this abstraction doesn’t force them to be either synchronous or asynchronous, it captures both.

Combining abstraction through received messages and rounds yields the Heard-Of model of Charron-Bost and Schiper [7]. It abstracts message-passing models through heard-of predicates, predicates over heard-of collections. A heard-of collection is a function/sequence of graphs capturing which messages are received across rounds in one execution. The Heard-Of model thus boils down the problem of comparing and ordering message-passing models to the one of comparing the corresponding heard-of predicate. But which heard-of predicate captures a given message-passing model? Heard-of predicates are properties of the rounds that can be implemented on top of the original model. Hence this question requires a system-level approach: looking for rules for when to change rounds that ensure that no process is blocked forever at a round.

In the synchronous case, where there is a bound on communication delay, every implementation of rounds used in the literature implements rounds by waiting for the bound. This ensures both the progress of rounds and the reception of every message from the round at that round. Since this gives the maximal information to each process at each round, this is the implementation of rounds on which the most problems can be solved. It thus makes sense to define the heard-of predicate characterizing a synchronous model as the one capturing this implementation: it simply specifies which messages can be lost or never sent, and have all the others received on the round they were sent.

On the other hand, by definition, asynchronous models lack any upper bound on communication delays. This results in a lot of variations on how rounds are implemented, depending on the model and the problem one is trying to solve. Waiting so little that the rule doesn’t block processes on any asynchronous model results in trivial heard-of predicates that
capture nothing specific about the model — for example the rule that always allows to change rounds. Conversely, rules that are tailored to a specific model, like waiting for \( n \) messages, might block processes in other models (where there might be less than \( n \) messages received at a round). Finding a corresponding heard-of predicate for an asynchronous model thus requires a model-specific analysis, as well as some way to choose among the possible rules. This paper proposes a formalisation of this question, as well as an approach for answering it for concrete message-passing models.

1.2. Overview. As mentioned above, abstracting message-passing models under one formalism would significantly help with comparing results across models and formally verifying them. The Heard-Of model provides such an abstraction, but only if we can define and compute a corresponding heard-of predicate for asynchronous message-passing models, which is the hardest case due to lack of an upper bound on communication delay. We compute this heard-of predicate in two steps, as shown in Figure 1. We start with the operational model, derive a “delivered predicate”, and then find the heard-of predicates that can be implemented by some rule for changing rounds (called a strategy) for this specific delivered predicate. Among such predicates, we propose a criterion to choose the one characterizing the asynchronous message-passing model.

The first step goes from the original asynchronous message-passing model to a delivered predicate, an abstraction that we introduce. A delivered predicate captures the messages that are eventually delivered from each round \( r \), without considering the round of delivery. This is to contrast with heard-of collections, that only capture messages tagged by \( r \) if delivered at the receiver when its local round counter is \( \leq r \). A delivered predicate makes the original model formal in the form of a delivered predicate, but it avoids dealing with the main issue for getting a heard-of predicate: asynchrony. Because the round of delivery is not considered in a delivered predicate, computing the corresponding one for our original model does not require a strategy for when to change rounds. Intuitively, the delivered predicate of a model is the heard-of predicate of the same model if it was synchronous, which are relatively straightforward to define and compute.

The second step goes from the delivered predicate to the heard-of predicate corresponding to the original model. To do so, we define strategies: rules that tell when processes can change rounds. The main constraint on such strategies is to never block a process at a round forever. As mentioned above, the difficulty here comes from the fact that there are in general many different strategies for implementing rounds that don’t block forever. Which of these should be the corresponding heard-of predicate? Our answer relies on the following intuition: the predicate precisely capturing the asynchronous model is the predicate satisfied by the fewer heard-of collections, among the set of predicates that can be implemented on top of the original model. Formally, this translates to being included in every other heard-of predicate that can be implemented (considering predicates as sets in the standard way). Such
a predicate, if it exists, intuitively constrains communication the most, by allowing fewer possibilities for which messages are heard by who at which round. This choice stems from the relevance of uncertainty for distributed computability. A distributed algorithm has to give the correct answer independently of the specific scheduling, the specific failures, and every other source of uncertainty and non-determinism specified by the model. This means that if everything that could happen according to model $M_1$ could also happen according to model $M_2$, then every correct algorithm for $M_2$ is also correct for $M_1$. In the Heard-Of model, this means that for two heard-of predicates $HO_1$ and $HO_2$ such that $HO_1 \subseteq HO_2$, then every correct algorithm for $HO_2$ is also correct on $HO_1$.

With this formalization in hand, what is left is a way to compute the resulting predicate and prove that it is indeed the strongest. This problem becomes tractable by introducing operations on predicates (delivered and heard-of) and strategies. Operations capture the intuition that it’s often easier to build complex models by composing simple ones together. Hence if the original model can be framed as such a composition, its delivered predicate can similarly be constructed from the delivered predicates of the building blocks, thanks to the operations we define. For some families of strategies (strategies that only depend on some limited part of the local state of a process, here the messages of the current round or the messages of past and current rounds respectively), the strategy that implements the heard-of predicate corresponding to the full model can be built from the strategies of the building blocks using analogous operations on strategies that we define. Then the heard-of predicate of this built strategy is linked with the composition of the heard-of predicates implemented by the building block strategies.

1.3. Contributions. The contributions of this article are the following:

- The definition of delivered predicates and strategies, in Section 3.
- Operations on delivered predicates and strategies, to build complex predicates, in Section 4.
- The formalization of the derivation of heard-of predicates from a delivered predicate and a strategy, in Section 5. This comes with a complete example: the asynchronous message-passing model with reliable communication and at most $F$ permanent crashes.
- The study of oblivious strategies, the strategies only looking at messages for the current round, in Section 6. We provide a technique to extract a strategy dominating the oblivious strategies of the complex predicate from the strategies of its building blocks; exact computations of the generated heard-of predicates; and a sufficient condition on the building blocks for the result of the operations to be dominated by an oblivious strategy.
- The study of conservative strategies, the strategies looking at all messages from previous and current round, as well as the round number, in Section 7. We provide a technique to extract a strategy dominating the conservative strategies of the complex predicate from the strategies of its building blocks; upper bounds on the generated heard-of predicates; and a sufficient condition on the building blocks for the result of the operations to be dominated by a conservative strategy.
- A preliminary exploration of strategies using messages from future rounds, and an extended example where these strategies build stronger heard-of predicates than oblivious and conservative strategies, in Section 8.
1.4. **Related Work.** Rounds in message-passing algorithms date at least back to their use by Arjomandi et al. [1] as a synchronous abstraction of time complexity. Since then, they are omnipresent in the literature. First, the number of rounds taken by a distributed computation is a measure of its complexity. Such round complexity was even developed into a full-fledged analogous of classical complexity theory by Fraigniaud et al. [12]. Rounds also serve as stable intervals in the dynamic network model championed by Kuhn and Osham [16]: each round corresponds to a fixed communication graph, the dynamicity following from possible changes in the graph from round to round. Finally, many fault-tolerant algorithms are structured in rounds, both synchronous [11] and asynchronous ones [4].

Although we only consider message-passing models in this article, rounds are also widely used in shared-memory models. A classic example is the structure of executions underlying the algebraic topology approach pioneered by Herlihy and Shavit [14], Saks and Zaharoglou [19], and Borowsky and Gafni [3].

Gafni [13] proposed a unification of all versions of rounds with the Round-by-Round Fault Detector abstraction, a distributed module analogous to a failure detector which outputs a set of suspected processes. In a system using RRFD, the end condition of rounds is the reception of a message from every process not suspected by the local RRFD module; communication properties are then defined as predicates on the output of RRFDs. Unfortunately, this approach fails to guarantee one property that will prove necessary in the rest of this paper: the termination of rounds.

Charron-Bost and Schiper [7] took a dual approach to Gafni’s work with the Heard-Of Model, by combining the concept of a fault model where the only information is which message arrives, from Santoro and Widmayer [20]. Instead of specifying communication by predicates on a set of suspected processes, they used heard-of predicates: predicates on a collection of heard-of sets, one for each round $r$ and each process $j$, containing every process from which $j$ received the message sent in round $r$ before the end of this same round. This conceptual shift brings two advantages: a purely abstract characterization of message-passing models and the assumption of infinitely many rounds, thus of round termination.

This model was put to use in many ways. Computability and complexity results were proven: new algorithms for consensus in the original paper by Charron-Bost and Schiper [7]; characterizations for consensus solvability by Coulouma et al. [8] and Nowak et al. [18]; a characterization for approximate consensus solvability by Charron-Bost et al. [6]; a study of $k$ set-agreement by Biely et al. [2]; and more. The clean mathematical abstraction of the Heard-Of model also works well with formal verification. The rounds provide structure, and the reasoning can be less operational than in many distributed computing abstractions. For instance, there exist a verification with the proof assistant Isabelle/HOL of consensus algorithms in Charron-Bost et al. [5], cutoff bounds for the model checking of consensus algorithms by Marić et al. [17], a DSL to write code following the structure of the Heard-Of model and verify it with inductive invariants by Drăgoi et al. [9].

Yet, determining which model implements a given heard-of predicate is an open question. As mentioned in Marić [17], the only known works addressing it, one by Hutle and Schiper [15] and the other by Drăgoi et al. [9], both limit themselves to specific predicates and partially synchronous system models.
2. The Heard-Of Model

In the Heard-Of model of Charron-Bost and Schiper [7], algorithms are defined by rounds, and an execution is an infinite sequence of rounds. At each round, a process broadcasts, receives, and does a local computation. The Heard-Of model ensures communication-closedness [10]: in an algorithm, processes at a given round only interact with processes at the same round — they only consider messages from this round. In the Heard-Of model, executions are necessarily infinite, and processes change rounds infinitely. Nevertheless, this does not prevent an algorithm from terminating, and, for instance to achieve consensus or election: the system reaches a configuration where the local state of each process does not change anymore.

The Heard-Of model constrains communication through heard-of predicates, which are themselves predicates on heard-of collections. These predicates play the role of assumptions about synchrony, faults, network topology, and more. Usually, heard-of collections are represented as functions from a round \( r \) and a process \( p \) to a set of processes — the processes from which \( p \) heard the message sent at round \( r \) before or during its own round \( r \).

**Definition 2.1** (Heard-Of Collection and Predicate). Let \( \Pi \) a set of processes. A heard-of collection is an element \( h \) of \((\mathbb{N}^* \times \Pi) \mapsto \mathcal{P}(\Pi)\). The heard-of sets of a heard-of collection are the outputs of this collection. A heard-of predicate \( \mathcal{H}(O) \) for \( \Pi \) is a set of heard-of collections, that is an element of \( \mathcal{P}((\mathbb{N}^* \times \Pi) \mapsto \mathcal{P}(\Pi)) \).

From another perspective, heard-of collections are infinite sequences of communication graphs — directed graphs which capture who hears from whom on time, in that \( q \in h(r,p) \iff (q,p) \) is an edge of the \( r \)-th communication graph.

**Definition 2.2** (Collection as a Sequence of Directed Graphs). Let Graphs\(\Pi\) be the set of directed graphs whose nodes are the elements of \( \Pi \). Then \( gr \in (\text{Graphs}\Pi)^\omega \) is a heard-of collection. A function \( h \) and a sequence \( gr \) represent the same collection when \( \forall r > 0, \forall p \in \Pi : h(r,p) = In_{gr}[r](p) \), where \( In[p] \) is the set of incoming neighbors of \( p \).

In general, which perspective to use in a theorem or a proof naturally follows from the context. For example, \( h[r] \) makes sense for a sequence of directed graphs, while \( h(r,p) \) makes sense for a function.

3. Delivered Predicates: Rounds Without Timing

Our concern is asynchronous message-passing models. What makes the synchronous case easier than the asynchronous case boils down to the equivalence between the messages that are received at all, and those that are received on time. This cannot be replicated in the asynchronous case, as each asynchronous model requires a different rule for which messages to wait for before changing round. For example, in an asynchronous model with at most \( F \) crashes, a process can wait for \( n - F \) messages before changing round without risking waiting forever, as at least \( n - F \) processes will never crash. In the asynchronous model with at most \( F + 1 \) crashes, doing so will get processes blocked in some cases. Nevertheless, it might be impossible to wait for all the messages that will be delivered and not block forever. As explained before, in an asynchronous model with at most \( F \) crashes, process wait for \( n - F \) messages before changing round. If less than \( F \) processes crash, not all the messages will be waited for: a process may change round as soon as it has received \( n - F \) messages, and some messages will be received too late and therefore be ignored.
3.1. Delivered Predicates. Delivered sets are introduced to distinguish between the set of all delivered messages (on time or late) and the messages delivered before changing round (a heard-of set). A delivered collection is a sequence of delivered sets, and a delivered predicate is a predicate on delivered collections that defines which messages are received, ignoring changes of rounds. Observe that a delivered predicate has the same formal definition as Definition 2.1 of heard-of predicates — only the interpretation changes —, and the graph-based notation similarly applies.

**Definition 3.1 (Delivered Collection and Predicate).** Let \( \Pi \) a set of processes. A **delivered collection** is an element \( c \) of \( (\mathbb{N}^* \times \Pi) \mapsto \mathcal{P}(\Pi) \). The **delivered sets** of a delivered collection are the outputs of this collection. A **delivered predicate** \( \text{DEL} \) for \( \Pi \) is a set of delivered collections, that is an element of \( \mathcal{P}(\mathcal{P}((\mathbb{N}^* \times \Pi) \mapsto \mathcal{P}(\Pi))) \).

For examining the difference between heard-of and delivered collections, recall that we’re considering the Heard-Of model at a system level: we’re implementing it. Let’s take an execution of some implementation (which needs to satisfy some constraints, defined later in Section 5.1): a linear order of emissions, receptions and changes of rounds (a step where the local round counter is incremented) for each process. Then if each process changes round infinitely often, there’s a delivered collection \( d \) and a heard-of collection \( h \) corresponding to this execution — just look at which messages sent to \( j \) tagged with round \( r \) where received at all by \( j \) (for \( d \)), and which were received when the round counter at \( j \) was \( \leq r \) (for \( h \)). That is, for a round \( r > 0 \) and processes \( k, j \in \Pi, k \in d(r, j) \) means that \( j \) received at some point the message of \( k \) annotated by \( r \). On the other hand, \( k \in h(r, j) \) means that \( j \) received the message of \( k \) annotated by \( r \) while its round counter was \( \leq r \). Hence the heard-of collection extracted from this execution captures which messages were waited for (and thus could be used at the algorithm level — that’s not treated here), whereas the delivered collection extracted from this execution captures which messages were received at all. For example, the following scenario:

```
  \[ k_1 \]
  \[ k_2 \]
  \[ k_3 \]
  \[ j \]
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leads to: \( \{k_1, k_2, k_3\} \subseteq d(r, j) \) and \( \{k_1, k_2\} \subseteq h(r, j) \).

To find the delivered predicate corresponding to an asynchronous model, the intuition is to take the synchronous version of the model, and then take the heard-of predicate that would be implemented by the rule for changing rounds in synchronous models. This is the delivered predicate for the model. This captures the strongest heard-of predicate that could be implemented on top of this asynchronous model, if processes could wait for all messages that will be delivered. In general, they can’t, since it requires knowing exactly what’s happening over the whole distributed system. Nonetheless, the delivered predicate exists, and it plays the role of an ideal to strive for. The characterizing heard-of predicate of a model will be the closest overapproximation of the delivered predicate that can actually be implemented.
3.2. A Delivered Predicate for at Most \( F \) Crashes. As a first example, we consider the asynchronous model with reliable communication, and at most \( F \) crash failures (where crashes can happen at any point).

**Definition 3.2 (\( \text{DEL}^{\text{crash}}_F \)).** The delivered predicate \( \text{DEL}^{\text{crash}}_F \) for the asynchronous model with reliable communication and at most \( F \) permanent crashes is defined as:

\[
\begin{align*}
\forall r > 0, \forall p \in \Pi : & \quad \text{card}(c(r, p)) \geq n - F \\
& \quad \text{AND} \\
& \quad c(r + 1, p) \subseteq K_c(r),
\end{align*}
\]

where \( K_c(r) \) is the kernel of \( c \) at round \( r \): \( K_c(r) \triangleq \bigcap_{p \in \Pi} c(r, p) \), and card is the cardinality function.

Charron-Bost and Schiper [7, Table 1] define it as the heard-of predicate of the synchronous version of this model. We now give an argument for why, if you take the asynchronous model with reliable communication, and at most \( F \) permanent crashes, and implement communication-closed rounds in any way that ensures an infinite number of rounds for every process, the messages received will form a delivered collection of \( \text{DEL}^{\text{crash}}_F \). In the other direction, every collection of \( \text{DEL}^{\text{crash}}_F \) captures the messages received in an execution of the implementation of rounds on top of the aforementioned asynchronous model.

- Let \( t \) be an execution of an implementation of communication-closed rounds on top of the asynchronous model above, with the condition of ensuring an infinite number of rounds. We consider that a crashed process is modelled as a silent process: a crashed process will still receive all messages after it crashes, but will never do anything else after it crashed. This is observationally indistinguishable for the other processes. Since every process that has not crashed broadcasts, this entails that every process will eventually hear the message from every non-crashed process at this round. Since there’s at most \( F \) crashes, that’s at least \( n - F \) messages per round. Hence \( \text{card}(c(r, j)) \geq n - F \) for every process \( j \) and round \( r \).

Also, if \( p \) hears from \( k \) at round \( r + 1 \), then \( k \) sent the message before crashing. This means \( k \) did not crash at its own round \( r \), and thus that the message it broadcast at that round \( r \) was sent, and eventually received by all processes. Hence \( c(r + 1, j) \subseteq K_c(r) \).

- Let \( c \) be a collection such that \( \forall r > 0, \forall p \in \Pi : \text{card}(c(r, p)) \geq n - F \land c(r + 1, p) \subseteq K_c(r) \).

This collection corresponds to the execution where the crashed processes are the ones that stop broadcasting. Because communication is reliable, \( k \notin c(r, p) \) means that \( k \) never sent its message to \( p \) tagged with \( r \). From the model this means that it crashed during its broadcast at round \( r \) or earlier. Each crash thus happens at the first round where the crashed process is not heard by everyone, after sending the messages that are actually received at this round.

Later in this article, the heard-of predicate characterizing this delivered predicate (the most constrained one) is derived. We mention it here, as a comparison [7]:

\[
\text{HO}_F \triangleq \{ h, \text{a heard-of collection} \mid \forall r > 0, \forall p \in \Pi : \text{card}(ho(r, p)) \geq n - F \}
\]

The difference lies in the kernel condition: \( \text{DEL}^{\text{crash}}_F \) ensures that if any message sent by \( p \) at round \( r \) is not eventually delivered, then no message will be delivered from \( p \) at rounds \( r \). Intuitively, \( p \) not broadcasting means that it crashed during round \( r \) or earlier, and that it will never send messages for the next rounds. However, this is not maintained by \( \text{HO}_F \), as the \( n - F \) messages that are waited for are not necessarily the same for each process. So \( k \) might wait for a message from \( p \) at round \( r \), but \( j \) might receive at least \( n - F \) messages at
3.3. A Delivered Predicate for at Most $L$ Losses. As a second example, we consider the asynchronous model without crashes, but with at most $L$ messages lost in the whole execution (of the system level implementation of rounds).

**Definition 3.3 ($\text{DEL}^{\text{loss}}_L$).** The delivered predicate $\text{DEL}^{\text{loss}}_L$ for the asynchronous model without crashes, and with at most $L$ message losses $\triangleq$

\[
\left\{ c, \text{a delivered collection} \mid \sum_{r > 0, p \in \Pi} (n - \text{card}(c(r, p))) \leq L \right\}.
\]

This one is not from Charron-Bost and Schiper [7], but we can apply the same reasoning as for the previous delivered predicate. Here the sum counts the number of messages that are never delivered. Since all the processes are correct, this corresponds to the number of lost messages. For $L = 1$, the best known strategy (to our knowledge) implements the heard-of predicate

\[
\left\{ h, \text{a heard-of collection} \mid \forall r > 0, \sum_{p \in \Pi} \text{card}(\Pi \setminus \text{ho}(r, p)) \leq 1 \right\}.
\]

What is lost in implementing a heard-of predicate on top of the delivered predicate $\text{DEL}^{\text{loss}}_1$ is that instead of losing only one message over the whole execution, there might be one loss per round. This is explained in Section 8.

4. Composing Delivered Predicates

Finding the delivered predicate for a complex model is difficult. However, simple models are relatively easy to characterize by a delivered predicate. This motivates the following proposal to solve the plain part of Figure 2: composing simple delivered predicates to derive complex delivered predicates. That way, there will be no need to define by hand the delivered predicates of complex models.

4.1. Introductory Example. Consider a system where one process might crash and may or may not recover later on\(^1\). In some sense, this behavior is defined by having the delivered collections for one possible crash that never recovers, and the delivered collections for one possible crash that must recover. This amounts to a union (or a disjunction); we write it $\text{DEL}^{\text{canrecover}}_1 \triangleq \text{DEL}^{\text{crash}}_1 \cup \text{DEL}^{\text{recover}}_1$. The first predicate of this union is $\text{DEL}^{\text{crash}}_1$, the

\(^1\)If it does, we can assume that its memory is intact and no messages received in the meantime are lost, but that’s not important for the system level implementation.
The complete system is thus described by \( \text{DEL}^{\text{recover}} \). Intuitively, a process that can crash but must recover afterward is described by the behavior of \( \text{DEL}^{\text{crash}} \) which is shifted to the behavior of \( \text{DEL}^{\text{total}} \) (the predicate where all the messages are delivered) after some time. We call this the succession of these predicates, and write it \( \text{DEL}^{\text{recover}} \triangleq \text{DEL}^{\text{crash}} \language{en} \text{DEL}^{\text{total}} \). Finally, imagine adding to this system another permanent crash. The full behavior is such that there might be one crashed process as constrained by \( \text{DEL}^{\text{crash}} \), and another crashed process as constrained by \( \text{DEL}^{\text{canrecover}} \). We call it the combination (or conjunction) of these predicates, and write it \( \text{DEL}^{\text{crash}} \times \text{DEL}^{\text{canrecover}} \). The complete system is thus described by \( \text{DEL}^{\text{crash}}(\text{DEL}^{\text{crash}} \land \text{DEL}^{\text{total}}) \cup \text{DEL}^{\text{crash}} \).

In the following, we also introduce an operator \( \omega \) to express repetition. For example, a system where, repeatedly, a process can crash and recover is \( \text{DEL}^{\text{crash}} \land \text{DEL}^{\text{total}}) \omega \).

### 4.2. Operations on predicates

Let’s now formally define these operations.

**Definition 4.1 (Operations on predicates).** Let \( P_1, P_2 \) be two delivered or heard-of predicates.

- The **union** of \( P_1 \) and \( P_2 \) is \( P_1 \cup P_2 \).
- The **combination** \( P_1 \times P_2 \triangleq \{ c_1 \times c_2 \mid c_1 \in P_1, c_2 \in P_2 \} \), where if \( c_1 \) and \( c_2 \) are two collections, \( \forall r > 0, \forall p \in \Pi : (c_1 \times c_2)(r, p) = c_1(r, p) \cap c_2(r, p) \).
- The **succession** \( P_1 \Rightarrow P_2 \triangleq \bigcup_{c_1 \in P_1, c_2 \in P_2} c_1 \Rightarrow c_2 \), with \( c_1 \Rightarrow c_2 \triangleq \{ c \mid \exists r \geq 0 : c = c_1[1, r], c_2 \} \) (\( c_1[1, 0] \) is the empty sequence).
- The **repetition** of \( P_1 \), \( (P_1)\omega \triangleq \{ c \mid \exists (c_i)_{i \in \mathbb{N}^*} : \exists (r_i)_{i \in \mathbb{N}^*} : r_1 = 0 \land \forall i \in \mathbb{N}^* : (c_i \in P_1 \land r_i < r_{i+1} \land c[r_i + 1, r_{i+1}] = c_i[1, r_{i+1} - r_i]) \} \).

The intuition behind these operations is the following:

- The union of two delivered predicates is equivalent to an OR on the two communication behaviors. For example, the union of the delivered predicate for one crash at round \( r \) and of the one for one crash at round \( r + 1 \) gives a predicate where there is either a crash at round \( r \) or a crash at round \( r + 1 \).
- The combination of two behaviors takes every pair of collections, one from each predicate, and computes the intersection of the graphs at each round. Meaning, it adds the loss of messages from both, to get both behaviors at once. For example, the combination of the delivered predicate for one crash at round \( r \) and of the one for one crash at round \( r + 1 \) gives a predicate where there is a crash at round \( r \) and a crash at round \( r + 1 \). Observe that combining \( \text{DEL}^{\text{crash}} \) with itself gives \( \text{DEL}^{\text{crash}} \omega \), the predicate with at most two crashes.
- For succession, the system starts with one behavior, then switches to another. The definition is such that if \( r = 0 \), then no prefix of \( c_1 \) is used (the first behavior never happens), but the second one must always happen. For example, the succession of \( \text{DEL}^{\text{crash}} \) (one possible crash) with \( \text{DEL}^{\text{total}} \) (no crash) is a possible crash that recovers.
- Repetition is the next logical step after succession: instead of following one behavior with another, the same behavior is repeated again and again. For example, taking the repetition of at most one crash results in a potential infinite number of crash-and-restart, with the constraint of having at most one crashed process at any time.
4.3. Basic blocks. The usefulness of these operations comes from allowing the construction of interesting predicates from few basic ones. Let’s take a simple family of basic blocks: $\text{DEL}^{\text{crash}}_{1,r}$, the delivered predicate of the model with at most one crash, at round $r$.

**Definition 4.2** (At most 1 crash at round $r$). $\text{DEL}^{\text{crash}}_{1,r} \triangleq$

$$ \left\{ c, \text{ a delivered collection} \mid \exists \Sigma \subseteq \Pi : \begin{array}{c} \text{card}(\Sigma) \geq n - 1 \\
\forall p \in \Pi : \begin{array}{c} \forall r' \in [1, r]: c(r', p) = \Pi \\
\forall r' > r : c(r', p) \supseteq \Sigma \\
\end{array} \end{array} \right\}.$$ 

In these predicates, before round $r$, every process receives every message. At round $r$ a crash might happen, which means that processes only receive messages from a subset $\Sigma$ of $\Pi$ of size $\text{card}(\Pi) - 1$ from round $r + 1$ onwards. The subtlety at round $r$ is that the crashed process (the only one in $\Pi \setminus \Sigma$) might crash while sending messages, and thus might send messages to some processes and not others.

Another fundamental predicate is the total one: the predicate containing a single collection $c_{\text{total}}$, the one where every process receives every message at every round.

**Definition 4.3** (Total delivered predicate). $\text{DEL}^{\text{total}} \triangleq \{ c_{\text{total}} \}$, where $c_{\text{total}}$ is the collection defined by $\forall r > 0, \forall p \in \Pi : c(r, p) = \Pi$.

Using these building blocks, many interesting and important delivered predicates can be built, as shown in Table 1. For example, let’s take $\text{DEL}^{\text{crash}}_{1}$, the predicate with at most one crash. If a crash happens, it happens at one specific round $r$. $\text{DEL}^{\text{crash}}_{1}$ is a disjunction for all values of $r$ of the predicate with at most one crash at round $r$; that is, the union of $\text{DEL}^{\text{crash}}_{1,r}$ for all $r$.

5. From Delivered Predicates to Heard-Of Predicates

After defining delivered predicates and discussing how to find and/or build them, the next step is to study the heard-of predicates that can be implemented over a given delivered predicate. This is the plain part of Figure 3, which works between two mathematical abstractions, and is formal. To do so, we start by defining executions on the delivered predicate: traces of the system’s behavior that can be analysed. Next, we define strategies, which capture the rules for changing rounds, and thus constrain possible executions to those where changes of rounds happen only when allowed by the strategy. If such a strategy never generates an execution where some process is blocked forever at a round, it is called valid, and implements a heard-of predicate (one collection per execution). Finding the heard-of predicate corresponding to a given delivered predicate then boils down to defining a partial order of valid strategies by way of their heard-of predicate, and taking the greatest element.
Description | Expression
--- | ---
At most 1 crash | $\text{DEL}_{1}^{\text{crash}} = \bigcup_{i=1}^{\infty} \text{DEL}_{1,i}^{\text{crash}}$

At most $F$ crashes | $\text{DEL}_{F}^{\text{crash}} = \bigotimes_{j=1}^{F} \text{DEL}_{1}^{\text{crash}}$

At most 1 crash, which will restart | $\text{DEL}_{1}^{\text{recover}} = \text{DEL}_{1}^{\text{crash}} \hookrightarrow \text{DEL}_{1}^{\text{total}}$

At most $F$ crashes, which will restart | $\text{DEL}_{F}^{\text{recover}} = \bigotimes_{j=1}^{F} \text{DEL}_{1}^{\text{recover}}$

At most 1 crash, which can restart | $\text{DEL}_{1}^{\text{canrecover}} = \text{DEL}_{1}^{\text{recover}} \cup \text{DEL}_{1}^{\text{crash}}$

At most $F$ crashes, which can restart | $\text{DEL}_{F}^{\text{canrecover}} = \bigotimes_{j=1}^{F} \text{DEL}_{1}^{\text{canrecover}}$

No bound on crashes and restart, with only 1 crash at a time | $\text{DEL}_{1}^{\text{recovery}} = (\text{DEL}_{1}^{\text{crash}})^{\omega}$

No bound on crashes and restart, with max $F$ crashes at a time | $\text{DEL}_{F}^{\text{recovery}} = \bigotimes_{j=1}^{F} \text{DEL}_{1}^{\text{recovery}}$

At most 1 crash, after round $r$ | $\text{DEL}_{1,\geq r}^{\text{crash}} = \bigcup_{i=r}^{\infty} \text{DEL}_{1,i}^{\text{crash}}$

At most $F$ crashes, after round $r$ | $\text{DEL}_{F,\geq r}^{\text{crash}} = \bigcup_{i=r}^{\infty} \text{DEL}_{F,i}^{\text{crash}}$

At most $F$ crashes with no more than one per round | $\text{DEL}_{F}^{\text{crash}\neq} = \bigcup_{i_1\neq i_2\neq\ldots\neq i_F}^{F} \bigotimes_{j=1}^{F} \text{DEL}_{1,i_j}^{\text{crash}}$

| Table 1: Delivered Predicates Built Using our Operations |

5.1. Executions. The theory of distributed computing relies on the concept of executions: traces of a system’s behavior, with enough detail to be formally analysed. Here, as we study the system-level implementation of the Heard-Of model, the executions we consider are not executions of an algorithm solving a distributed computing problem, but the executions of the implementation of a specific heard-of predicate. Hence, these executions only track emissions, receptions and changes of rounds. Because the content of each message is not important for the implementation of rounds, and we care about which messages will be received on time, the emissions are implicit: as long as a process changed round $r - 1$ times, it sent its messages for round $r$ (which messages will depend on the delivered collection used, as explained in a few paragraphs). As for the local state of each process during this implementation, it contains a local round counter and the set of received messages.

The last thing that is missing here is the implementation algorithm: the rule that specifies when to change rounds. This is called a strategy, and is defined below. First, we define executions as sequences of events that satisfy some basic constraints on the ordering of events. We then constrain them by requiring the delivery of exactly the messages from some delivered collection. The introduction of strategies constrains them some more, so that the executions allowed are the executions of an implementation of rounds using this strategy.
Executions are infinite sequences of events, either delivery of messages \(\text{deliver}(r, k, j)\), which represents the delivery at \(j\) of the message from \(k\) tagged with \(r\), change to the next round for some process \(j\) \((\text{next}_j)\), which also includes the broadcast for the next round, or a deadlock \((\text{stop})\). An execution must satisfy three rules: no message is delivered before it is sent, no message is delivered twice, and once there is a \(\text{stop}\), the rest of the sequence can only be \(\text{stop}\).

**Definition 5.1** (Execution). Let \(\Pi\) be a set of \(n\) processes. Let the set of transitions \(T = \{\text{next}_j \mid j \in \Pi\} \cup \{\text{deliver}(r, k, j) \mid r \in \mathbb{N}^* \land k, j \in \Pi\} \cup \{\text{stop}\}\). Then, \(t \in T^\omega\) is an **execution** \(\triangleq\)

- (Delivery after sending)
  \(\forall i \in \mathbb{N} : t[i] = \text{deliver}(r, k, j) \implies \text{card}(\{l \in [0, i] \mid t[l] = \text{next}_k\}) \geq r - 1\)
- (Unique delivery)
  \(\forall (r, k, j) \in (\mathbb{N}^* \times \Pi \times \Pi) : \text{card}(\{i \in \mathbb{N} \mid t[i] = \text{deliver}(r, k, j)\}) \leq 1\)
- (Once stopped, forever stopped)
  \(\forall i \in \mathbb{N} : t[i] = \text{stop} \implies \forall l \geq i : t[l] = \text{stop}\)

Executions can be constrained by a delivered collection \(c\): if \(k\) changes round at least \(r - 1\) times in the execution, then it sends all the messages tagged with \(r\) to processes \(j\) satisfying \(k \in c(r, j)\), and these messages are delivered in the execution. Moreover, every delivery must be of such a message. The executions of a delivered predicate are the executions of the collections of the predicate.

**Definition 5.2** (Execution of a delivered collection (and of a predicate)). Let \(c\) be a delivered collection. Then, \(\text{execs}(c)\), the **executions of \(c\)** \(\triangleq\)

\[
\begin{cases}
  t, \text{ an execution} & \forall (r, k, j) \in \mathbb{N}^* \times \Pi \times \Pi : \\
  \quad (k \in c(r, j) \land \text{card}(\{i \in \mathbb{N} \mid t[i] = \text{next}_k\}) \geq r - 1) & \iff \\
  \quad (\exists i \in \mathbb{N} : t[i] = \text{deliver}(r, k, j))
\end{cases}
\]

For a delivered predicate \(\text{DEL}\), we write \(\text{execs}(\text{DEL}) = \bigcup_{c \in \text{DEL}} \text{execs}(c)\).

Definition 5.1 above casts behavior in term of changes to the system — the deliveries and changes of rounds. A dual perspective interprets behavior as the sequence of successive states of the system. In a distributed system, such states are the product of local states. The local state of a process is the pair of its current round and all the received messages up to this point\(^2\). Notably, such a local state doesn’t contain the identity of the process. This is both because we never need this identity, and because not dealing with it allows an easier comparison of local states, since two distinct processes can have the same local state. A message is represented by a pair \(\langle\text{round}, \text{sender}\rangle\) (instead of triplet like in deliver events, because the receiver is implicit — it’s the process whose local state we’re looking at). For a state \(q\), \(q(r)\) is the set of peers from which the process (with state \(q\)) has received a message tagged with round \(r\).

**Definition 5.3** (Local State). Let \(Q = \mathbb{N}^* \times \mathcal{P}(\mathbb{N}^* \times \Pi)\). Then \(q \in Q\) is a **local state**

For \(q = \langle r, \text{mes} \rangle\), we write \(q.\text{round}\) for \(r\), \(q.\text{mes}\) for \(\text{mes}\) and \(\forall r' > 0 : q(r') \triangleq \{k \in \Pi \mid \langle r', k \rangle \in q.\text{mes}\}\).

\(^2\)Recall that this is the local state of the system-level implementation of rounds, not of the algorithm running on top of the Heard-Of model. Hence, this doesn’t constrain the internal structure of the algorithms.
Let $t$ be an execution, $p \in \Pi$ and $i \in \mathbb{N}$. Then the local state of $p$ in $t$ after the prefix of $t$ of size $i$ is $q^t_p[i] \triangleq (\text{card}\{l < i \mid t[l] = \text{next}_p\}) + 1, \{\langle r, k \rangle \mid \exists l < i : t[l] = \text{deliver}(r, k, p)\})$.

Notice that such executions do not allow a process to “jump” from say round 5 to round 9 without passing by the rounds in-between. Indeed, the Heard-Of model doesn’t let processes decide when to change rounds: processes specify only which messages to send depending on the state, and what is the next state depending on the current state and the received messages. So it makes sense for a system-level implementation of heard-of predicates to do the same. Nevertheless, the algorithm running on top of the Heard-Of model can “jump” rounds, by not doing anything for a certain number of rounds.

5.2. Strategies and Composition of Strategies. An execution of a delivered collection where all processes change round infinitely often defines a heard-of collection. This is done by looking, for each round $r$ and process $p$, at the set of processes such that $p$ received their message tagged by $r$ when the round counter at $p$ was $\leq r$. However, not all of the executions, as defined in 5.2, ensure an infinite number of rounds for each process. For example, for a delivered collection $c$, the execution where all messages from round 1 are delivered according to $c$ (whatever the order) and then stop transitions happen forever is an execution of $c$. Yet it blocks all processes at round 1 forever. Strategies are introduced to solve this problem: they constrain executions. A strategy is a set of states from which a process is allowed to change round. It can also be seen as a predicate on local states. It captures rules such as “wait for at least $F$ messages from the current round”, or “wait for these specific messages”. Again, not all strategies lead to executions with an infinite number of rounds. We then consider valid strategies, which are strategies that ensure the resulting executions always contain an infinite number of rounds for each process.

**Definition 5.4 (Strategy).** $f \subseteq Q$ is a strategy.

Strategies as defined above are predicates on states\(^3\). This makes them incredibly expressive, but this expressivity creates difficulty in reasoning about them. To address this problem, we define families of strategies. Intuitively, strategies in a same family depend on a specific part of the state — for example the messages of the current round. Equality of these parts of the state defines an equivalence relation; the strategies of a family are strategies such that if a state $q$ is in the strategy, then all states in the equivalence class of $q$ are in the strategy.

**Definition 5.5 (Families of strategies).** Let $\approx$ be an equivalence relation on $Q$. The family of strategies defined by $\approx$, $\text{family}(\approx) \triangleq \{f, \text{a strategy} \mid \forall q_1, q_2 \in Q : q_1 \approx q_2 \implies (q_1 \in f \iff q_2 \in f)\}$.

Let’s define the executions of a strategy. The intuition is simple: every change of rounds (an event $\text{next}_k$ for a process $k$) happens only if the local state of the process is in the strategy. There is a fairness assumption that ensures that if the local state of some process $k$ is eventually continuously in the strategy, then it will eventually change round (have a $\text{next}_k$ event)\(^4\). A subtlety hidden in this obvious intuition is that the check for changing round

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\(^3\)One limiting case is for the strategy to be empty — the predicate being just $\text{False}$. This strategy is useless, and will be weeded out by the constraint of validity from Definition 5.7.

\(^4\)This is a weak fairness assumption, which requires a constant availability of the transition after some point to ensure it will happen. This is to be contrasted with a strong fairness assumption, which requires the availability infinitely often after some point to ensure that the transition will happen.
(whether the local state is in the strategy) doesn’t necessarily happen at each reception; it can happen at any point. This captures an asynchronous assumption where processes do not decide when they are executed.

**Definition 5.6 (Executions of a Strategy).** Let \( f \) be a strategy and \( t \) an execution. Then \( t \) is an execution of \( f \) if \( t \) satisfies:

- (All nexts allowed) \( \forall i \in \mathbb{N}, \forall p_i \in P : (t[i] = next_p_i \implies q_p_i[i] \in f) \),
- (Fairness) \( \forall p \in P : \text{card}(|\{i \in \mathbb{N} | t[i] = next_p\}|) < \infty \implies \text{card}(|\{i \in \mathbb{N} | q_p[i] \notin f\}|) = \infty \).

For a delivered predicate \( \text{DEL} \), \( \text{execs}_f(\text{DEL}) \triangleq \{ t | t \text{ an execution of } f \land t \in \text{execs}(\text{DEL}) \} \).

The first property states that processes only change round (the \( \text{next} \) transition) when their local state is in the strategy. Fairness ensures that the only way for a process \( p \) to be blocked at a round \( r \) is for \( p \)'s local state to not be in \( f \) an infinite number of times. If the local state of \( p \) is outside of \( f \) only a finite number of times, the local state of \( p \) is eventually always in \( f \), and the execution must contain another \( \text{next}_p \).

Going back to strategies, not all of them are equally valuable. In general, strategies with executions where processes are blocked forever at some round are less useful (to implement infinite sequences of rounds) than strategies without such executions. The validity of a strategy captures the absence of such an infinite wait.

**Definition 5.7 (Validity).** An execution \( t \) is valid if \( \forall p_i \in P, \forall N > 0, \exists i \geq N : t[i] = \text{next}_p_i \).

Let \( \text{DEL} \) a delivered predicate and \( f \) a strategy. Then \( f \) is a valid strategy for \( \text{DEL} \) if \( \forall t \in \text{execs}_f(\text{DEL}) \), \( t \) is a valid execution.

Finally, analogous to how we can combine complex predicates through operations, we can also compose complex strategies through similar operations:

**Definition 5.8 (Operations on strategies).** Let \( f_1, f_2 \) be two strategies. The following operations are defined:

- Their **union** \( f_1 \cup f_2 \).
- Their **combination** \( f_1 \otimes f_2 \triangleq \{ q_1 \otimes q_2 | q_1 \in f_1 \land q_2 \in f_2 \land q_1.\text{round} = q_2.\text{round} \} \), where for \( q_1 \) and \( q_2 \) at the same round \( r \), \( q_1 \otimes q_2 \triangleq \{ (r', k) | r' > 0 \land k \in q_1(r') \cap q_2(r') \} \).
- Their **succession** \( f_1 \Rightarrow f_2 \triangleq f_1 \cup f_2 \cup \{ q_1 \Rightarrow q_2 | q_1 \in f_1 \land q_2 \in f_2 \} \) where \( q_1 \Rightarrow q_2 \triangleq \langle q_1.\text{round} + q_2.\text{round}, \{ (r, k) | r > 0 \land \begin{cases} k \in q_1(r) & \text{if } r \leq q_1.\text{round} \\ k \in q_2(r - q_1.\text{round}) & \text{if } r > q_1.\text{round} \end{cases} \} \} \).
- The **repetition** of \( f_1 \), \( f_1^\ast \triangleq \{ q_1 \Rightarrow q_2 \Rightarrow \cdots \Rightarrow q_k | k \geq 1 \land q_1, q_2, \ldots, q_k \in f_1 \} \).

The intuition behind these operations is analogous to the ones for predicates:

- The union of two strategies is equivalent to an OR of the two conditions. For example, the union of waiting for at least \( n - F \) messages and waiting for all messages but the ones from \( p_1 \) gives a strategy that accepts change of round when more than \( n - F \) messages are received or when all messages except the one from \( p_1 \) are received.
- The combination of two strategies takes all intersections of local states in the first strategy and local states in the second. For example, combining the strategy that waits at least \( n - 1 \) messages for the current round with itself will wait for at least \( n - 2 \) messages.
- For succession, the states accepted are those where messages up to some round correspond to an accepted state of the first strategy, and messages from this round up correspond to an accepted state of the second strategy.
Repetition is the next logical step after succession: instead of following one strategy with another, the same strategy is repeated again and again.

5.3. Extracting Heard-Of Collections of Executions. If an execution is valid, then all processes go through an infinite number of rounds. That is, it captures the execution of a system-level implementation of rounds where no process blocks forever at some round. It thus makes sense to speak of the heard-of collection implemented by this execution: at the end of round $r$ for process $p$, the messages from round $r$ that were received by $p$ define the heard-of set for $r$ and $p$.

**Definition 5.9** (Heard-Of Collections Generated by Executions and Heard-Of Predicate Generated by Strategies). Let $t$ be a valid execution. Then the **heard-of collection generated by** $t$, $h_t \triangleq \forall r \in \mathbb{N}^*, \forall p \in \Pi : h_t(r, p) = \left\{ k \in \Pi : \exists i \in \mathbb{N} : \left( \begin{array}{c} q^p[i].round = r \\ t[i] = next_p \\ \langle r; k \rangle \in q^p[i].mes \end{array} \right) \right\}$.

Let $DEL$ be a delivered predicate, and $f$ be a valid strategy for $DEL$. Then the **heard-of predicate generated by** $f$ on $DEL \triangleq \mathcal{HO}_f(DEL) \triangleq \{ h_t | t \in \text{execs}_f(DEL) \}$.

As the strategy is valid, this definition is well-founded and the strategy generates a heard-of predicate from the delivered predicate.

5.4. Dominating Predicate. The way to go from a delivered predicate to a heard-of one is to design a valid strategy for the former that generates the latter. With different strategies, different heard-of predicates can be generated. Which one should be considered as the characterization of the delivered predicate (and of the corresponding operational model)? A heard-of predicate generated from a delivered predicate is an over-approximation of the latter. To be able to solve as many problems as possible, as many messages as possible should be received on time. The characterizing heard-of predicate is thus the smallest such over-approximation of the delivered predicate, if it exists. This intuition is formalized by defining a partial order on valid strategies for a delivered predicate, capturing the implication of the generated heard-of predicates (the inclusion when considered as sets). One strategy dominates another if the heard-of collections it generates are also generated by the other. Dominating strategies are then the greatest elements for this order. By definition of domination, all dominating strategies generate the same dominating heard-of predicate, which characterizes the delivered predicate.

**Definition 5.10** (Domination Order, Dominating Strategy and Dominating Predicate). Let $DEL$ be a delivered predicate and let $f$ and $f'$ be two valid strategies for $DEL$. Then, $f$ **dominates** $f'$ for $DEL$, written $f' \prec_{DEL} f$, if $\mathcal{HO}_{f'}(DEL) \supseteq \mathcal{HO}_f(DEL)$. A greatest element for $\prec_{DEL}$, if it exists, is called a **dominating strategy** for $DEL$. Given such a strategy $f$, the **dominating predicate** for $DEL$ is then $\mathcal{HO}_f(DEL)$. 
5.5. **Standard and Canonical Executions.** In the following sections, we prove properties about dominating strategies, their invariance by the operations, and the heard-of predicates that they generate. These proofs rely on reasoning by contradiction: assume the theorem or lemma is false, and derive a contradiction. These contradictions take the form of proving that a valid strategy has an invalid execution; constructing specific executions is therefore the main technique in these proofs. This section introduces two patterns for constructing executions: one from a delivered collection and a strategy, and the other from a heard-of collection.

To do so, let’s fix ord as some function taking a set and returning an ordered sequence of its elements — the specific ordering doesn’t matter. This will be used to ensure the uniqueness of the executions, but the order has no impact on the results.

5.5.1. **Standard Execution.** The standard execution extracts an execution from a delivered collection. It follows a loop around a simple pattern: deliver all the messages that were sent according to the delivered collection, then change round for all the processes which are allowed to do so by f. The intuition is that it’s the simplest way to specify an execution where strategies that look only at messages from current and previous rounds (as studied later) always have all the information available to them. This means that if at one point a first process fails to change round while using such a strategy, it will be blocked at this round for the rest of the standard execution.

Given elements $x_1, x_2, x_3, \ldots$, the notation $\prod_{i \in \mathbb{N}^*} x_i$ is the infinite concatenation $x_1x_2x_3\ldots$

**Definition 5.11 (Standard Execution of a Strategy on a Collection).** Let c be a delivered collection, and f be a strategy. The **standard execution of f on c** is $st(f, c) \triangleq \prod_{r \in \mathbb{N}^*} dels_r, changes_r$, where

- $dels_1 \triangleq \text{ord}\{\text{deliver}(1, k, j) \mid k \in c(1, j)\}$, the ordered sequence of deliveries for messages from round 1 that will be delivered eventually according to c.
- $changes_1 \triangleq \text{ord}\{\text{next}_j \mid \{1, \{(1, k) \mid k \in c(1, j)\}\} \in f\}$, the ordered sequence of next transitions for processes for which the state resulting from the deliveries in dels$_1$ is in $f$.
- $\forall r > 1 : dels_r \triangleq \text{ord}\{\text{deliver}(\text{round}_r^k, k, j) \mid \text{next}_k \in changes_{r-1} \wedge k \in c(\text{round}_r^k, j)\}$, with $\text{round}_r^k \triangleq 1 + \sum_{r' \in [1, r]} \text{card}\{\text{next}_k \cap \text{changes}_{r'}\}$.

This is the ordered sequence of deliveries of messages from processes that changed round during changes$_{r-1}$.
- $\forall r > 1 : changes_r \triangleq \{\text{ord}\{\text{next}_j \mid \{(\text{round}^l_r, \{r', k \mid \text{deliver}(r', k, j) \in \bigcup_{r'' \in [1, r]} \text{dels}_{r''}\}\} \in f\}$ if it is not empty
- $\text{ord}\{\text{stop}\}$ otherwise

with $\text{round}^l_r \triangleq 1 + \sum_{r' \in [1, r]} \text{card}\{\text{next}_j \cap \text{changes}_{r'}\}$.

This is the ordered sequence of changes of round for processes such that their state after the deliveries of dels$_r$ is in $f$.

The main property of a standard execution of f on c is that it is both an execution of f and an execution of c.

**Lemma 5.12 (Correctness of Standard Execution).** Let c be a delivered collection and f be a strategy. Then $st(f, c) \in execs_f(c)$.
Proof idea. First, the proof shows that \( st(f, c) \) is indeed an execution by verifying the three properties of Definition 5.1. Then, it shows that \( st(f, c) \) is an execution of the delivered collection \( c \) (Definition 5.2: the delivered messages in \( st(f, c) \) are exactly those from \( c \)). Lastly the verification of the two conditions of Definition 5.6 ensures that \( st(f, c) \) is an execution of strategy \( f \). This proof is trivial but verbose, and is presented in Appendix A.1.

5.5.2. Canonical Execution. Whereas the standard execution captures a straightforward way to create an execution from a strategy and a delivered collection, this new construction starts with a heard-of collection, and creates a valid execution generating it from the total delivered collection (the one with all the receptions). The link between the two is that when we want to prove that a valid strategy \( f \) implements a heard-of collection \( ho \) (useful for showing dominance of strategies), we show by contradiction that the canonical execution of \( ho \) is an execution of \( f \). Since the proof by contradiction assumes that one of the next \( j \) transitions in the canonical execution is not allowed by \( f \), we can usually find a delivered collection where the messages delivered at this point are the only ones that will ever be delivered to \( j \), and so show that the standard execution of this delivered collection is not valid, which contradicts the validity of \( f \).

This canonical execution follows a simple pattern: at each round, deliver all the messages from the heard-of sets of this round, and also all the messages undelivered from the previous round (the ones that were not in the heard-of sets of the previous round).

Definition 5.13 (Canonical Execution of a Heard-Of Collection). Let \( ho \) be a heard-of collection. The canonical execution of \( ho \) is \( can(ho) \triangleq \prod_{r \in \mathbb{N}} dels_r, changes_r \), where

- \( dels_1 \triangleq ord(\{deliver(1,k,j) \mid k \in ho(1,j)\}) \), the ordered sequence of deliveries that happen at round 1 in \( h \).
- \( \forall r > 1 : dels_r \triangleq ord(\{deliver(r,k,j) \mid k \in ho(r,j)\} \cup \{deliver(r-1,k,j) \mid k \in \Pi \setminus ho(r-1,j)\}) \), the ordered sequence of deliveries that happen at round \( r \) in \( h \).
- \( \forall r > 0 : changes_r \triangleq ord(\{next_k \mid k \in \Pi\}) \), the ordered sequence of next transitions, one for each process.

This canonical execution is an execution of any delivered predicate containing \( c_{total} \), the collection where every message is delivered. Having this collection in a delivered predicate ensures that although faults might happen, they are not forced to do so.

Lemma 5.14 (Canonical Execution is an Execution of Total Collection). Let \( ho \) be a heard-of collection. The canonical execution \( can(ho) \) of \( ho \) is an execution of \( c_{total} \).

Proof. First, \( can(ho) \) is an execution by Definition 5.1 since it satisfies the three conditions:

- Delivered only once: Every sent message is delivered either during the round it was sent or during the next one, and thus delivered only once.
- Delivered after sending: Every message from round \( r \) is delivered after either \( r - 1 \) or \( r \) next \( p \) transitions for the sender \( p \), which means at round \( r \) or \( r + 1 \). Hence the message is delivered after being sent.
- Once stopped, forever stopped: No process stops, so the last condition for executions is trivially satisfied.

Furthermore, for each process \( p \) and round \( r \), all the messages from \( p \) at round \( r \) are delivered in \( can(ho) \), either at round \( r \) or at round \( r + 1 \). Since the total collection is the collection
where every message is delivered by Definition 4.3, this entails that \( \text{can}(\text{ho}) \) is an execution of the total delivered collection by Definition 5.2, and thus an execution of \( \text{DEL} \).

Lastly, the whole point of the canonical execution of \( \text{ho} \) is that it generates \( \text{ho} \).

**Lemma 5.15** (Canonical Execution Generates its Heard-Of Collection). Let \( \text{ho} \) be a heard-of collection. Then \( h_{\text{can}(\text{ho})} = \text{ho} \).

*Proof.* Let \( r > 0 \) and \( j \in \Pi \). Let’s prove that \( h_{\text{can}(\text{ho})}(r,j) = \text{ho}(r,j) \).

- \( \subseteq \) Let \( p \in h_{\text{can}(\text{ho})}(r,j) \), let’s prove that \( p \in \text{ho}(r,j) \). Since \( p \in h_{\text{can}(\text{ho})}(r,j) \), Definition 5.9 gives: \( \exists i \in \mathbb{N} : q^\text{can}(\text{ho})[i].\text{round} = r \land \text{can}(\text{ho})[i] = \text{next}_j \land \langle r, p \rangle \in q^\text{can}(\text{ho})[i].\text{mes} \).
  - Since \( q^\text{can}(\text{ho})[i].\text{round} = r \), Definition 5.3 gives \( \text{card}\{l < i : \text{can}(\text{ho})[l] = \text{next}_j\} = r - 1 \).
  - Definition 5.13 implies that \( \text{next}_j \) appears only in the changes sequences, and only once in each changes. So, since \( \text{can}(\text{ho})[i] = \text{next}_j \) and \( \text{card}\{l < i : \text{can}(\text{ho})[l] = \text{next}_j\} = r - 1 \), then \( \text{can}(\text{ho})[i] \) is in changes, and so is between dels and dels\(_{r+1} \).
  - Since \( \langle r, p \rangle \in q^\text{can}(\text{ho})[i].\text{mes} \) and \( \text{can}(\text{ho})[i] \) is between dels\(_r \) and dels\(_{r+1} \), Definition 5.13 implies that \( p \in \text{ho}(r,j) \).

- \( \supseteq \) Let \( p \in \text{ho}(r,j) \), let’s prove that \( p \in h_{\text{can}(\text{ho})}(r,j) \), i.e., (Definition 5.9) \( \exists i \in \mathbb{N} : q^\text{can}(\text{ho})[i].\text{round} = r \land \text{can}(\text{ho})[i] = \text{next}_j \land \langle r, p \rangle \in q^\text{can}(\text{ho})[i].\text{mes} \). Let \( i \) the index of changes, such that \( \text{can}(\text{ho})[i] = \text{next}_j \). Definition 5.13 ensures such an \( i \) exists since in each changes, there is a next\(_k \) for each \( k \in \Pi \).
  - Definition 5.13 ensures that there are \( r - 1 \) next\(_j \) transitions in \( \text{can}(\text{ho}) \) before index \( i \), so \( q^\text{can}(\text{ho})[i].\text{round} = r \).
  - By definition of \( i \), \( \text{can}(\text{ho})[i] = \text{next}_j \).
  - Definition 5.13 ensures that dels\(_r \) is before changes in \( \text{can}(\text{ho}) \). Since \( p \in \text{ho}(r,j) \), so deliver\((r,p,j)\) appears in \( \text{can}(\text{ho}) \) before index \( i \) and so \( \langle r, p \rangle \in q^\text{can}(\text{ho})[i].\text{mes} \). \( \square \)

5.6. A Complete Example: At Most \( F \) Crashes. Let’s look at a concrete example to get a better grasp at how all these concepts work together, and the kind of results they allow us to prove. We consider \( \text{DEL}^\text{crash}_F \) from Definition 3.2, the message-passing model with asynchronous and reliable communication, and at most \( F \) permanent crashes. We now give a dominating strategy for this predicate, as well as compute its heard-of predicate. The folklore strategy for this model is to wait for at least \( n - F \) messages before allowing the change of round.

**Definition 5.16** (waiting for \( n - F \) messages). The strategy to wait for \( n - F \) messages is \( f_{n-F} \triangleq \{ q \in Q \mid \text{card}\{k \in \Pi \mid \langle q.\text{round}, k \rangle \in q.\text{mes}\} \geq n - F \} \).

To see why this strategy is used in the literature, remark that at least \( n - F \) messages must be delivered to each process at each round. Thus, waiting for that many messages ensures that no process is ever blocked. However, waiting for more will result in processes blocking forever if \( F \) crashes occur. Rephrased with the concepts introduced above, \( f_{n-F} \) is a valid and dominating strategy for \( \text{DEL}^\text{crash}_F \).

**Lemma 5.17** (Validity of \( f_{n-F} \)). \( f_{n-F} \) is valid for \( \text{DEL}^\text{crash}_F \).
Proof. We proceed by contradiction. Assume \( f_{n-F} \) is invalid for \( \text{DEL}^{\text{crash}} \). By Definition 5.17, there exists an invalid \( t \in \text{execs}_{f_{n-F}}(\text{DEL}^{\text{crash}}_F) \). By Definition 5.17 of validity, \( \exists p \in \Pi, \exists N, \forall i \geq N : t[i] \neq \text{next}_p \); there is a smallest round \( r \) such that some process \( j \) stays blocked at \( r \) forever in \( t \). Because \( t \) is an execution of \( f \), Definition 5.6 entails that infinitely many local states of \( j \) must be not in \( f_{n-F} \); if it was not the case, the fairness condition would force the execution to contain another \( \text{next}_j \). Let also \( c_t \) be a delivered collection of \( \text{DEL}^{\text{crash}}_F \) such that \( t \in \text{execs}(c) \). We know by Definition 3.2 of \( \text{DEL}^{\text{crash}}_F \) that \( \text{card}(c_t(r,j)) \geq n - F \). The minimality of \( r \) and the fact that \( t \in \text{execs}(c) \) ensure by Definition 5.2 that all the messages in this delivered set are delivered at some point in \( t \). By Definition 5.16 of \( f_{n-F} \), the local state of \( j \) is then in \( f_{n-F} \) from this point on. By the fairness constraint of Definition 5.6, this contradicts the fact that there is never another \( \text{next}_j \) in the suffix of \( t \). We conclude that \( f_{n-F} \) is valid for \( \text{DEL}^{\text{crash}}_F \). \( \square \)

The next step is to prove that this strategy is dominating the predicate. We first need to compute the heard-of predicate generated by \( f_{n-F} \). This heard-of predicate was given by Charron-Bost and Schiper [7] as a characterization of the asynchronous model with reliable communication and at most \( F \) crashes, without a formal proof. The intuition behind it is that even in the absence of crashes, we can make all the processes change round by delivering any set of at least \( n - F \) messages to them.

**Theorem 5.18** (Heard-Of predicate of \( f_{n-F} \)).

Let \( \text{HO}_F \) be the heard-of predicate defined as \( \{ h, \text{a heard-of collection} \mid \forall r > 0, \forall p \in \Pi : \text{card}(ho(r,p)) \geq n - F \} \). Then \( \text{HO}_{f_{n-F}}(\text{DEL}^{\text{crash}}_F) = \text{HO}_F \).

Proof.

- \((\subseteq)\). Let \( ho \in \text{HO}_{f_{n-F}}(\text{DEL}^{\text{crash}}_F) \) and \( t \in \text{execs}_{f_{n-F}}(\text{DEL}^{\text{crash}}_F) \) an execution of \( f_{n-F} \) generating \( ho \). By Definition 5.6 of the executions of \( f_{n-F} \), processes change round (a \( \text{next}_k \) event) only when their local state is in \( f_{n-F} \). By Definition 5.16, this means that this local state \( q \) satisfies \( \text{card}([k \in \Pi \mid \{q.round, k \} \in q.mes]) \geq n - F \): the process received at least \( n - F \) messages tagged with the current value of its round counter. This in turns implies by Definition 5.9 of the heard-of collection of an execution that \( \forall r \in \mathbb{N}^*, \forall j \in \Pi : \text{card}(ho(r,j)) \geq n - F \).

- \((\supseteq)\). Let \( ho \) a heard-of collection over \( \Pi \) such that \( \forall r \in \mathbb{N}, \forall j \in \Pi : \text{card}(ho(r,j)) \geq n - F \). Let \( t \) be the canonical execution of \( ho \); since \( \text{DEL}^{\text{crash}}_F \) contains the total collection, \( t \) is an execution of \( \text{DEL}^{\text{crash}} \) by Lemma 5.14. To prove that \( t \) is also an execution of \( f_{n-F} \), we proceed by contradiction. Assume it is not an execution of \( f_{n-F} \). By Definition 5.6, the problem stems either from breaking fairness or from some \( \text{next}_p \) for some \( p \) at a point where the local state of \( p \) is not in \( f_{n-F} \). Since by Definition 5.13 of a canonical execution, \( \forall p \in \Pi : \text{next}_p \) appears an infinite number of times, the only possibility left is the second one: there is some \( p \in \Pi \) and some \( \text{next}_p \) transition in \( t \) that happens while the local state of \( p \) is not in \( f_{n-F} \). Let \( r \) be the smallest round where this happens, and \( j \) the process to which it happens. By Definition 5.13 of a canonical execution, \( j \) received all the messages from \( ho(r,j) \) in \( t \) before the problematic \( \text{next}_j \). By hypothesis, \( \text{card}(ho(r,j)) \geq n - F \). By Definition 5.16 of \( f_{n-F} \), the local state of \( j \) is in \( f_{n-F} \) from this point on. By the fairness constraint of Definition 5.6, this contradicts the fact that \( j \) cannot change round at this point in \( t \). Hence \( t \) is an execution of \( f_{n-F} \).

We conclude that \( ho \in \text{HO}_{f_{n-F}}(\text{DEL}^{\text{crash}}_F) \). \( \square \)
Finally, we want to vindicate the folklore intuition about this strategy: that it is optimal in some sense. Intuitively, waiting for more than \( n - F \) messages per round means risking waiting forever, and waiting for less is wasteful. Our domination order captures this concept of optimality: we show that \( f_{n-F} \) is indeed a dominating strategy for \( \text{DEL}_F^{\text{crash}} \). Therefore, \( \mathcal{HO}_{f_{n-F}}(\text{DEL}_F^{\text{crash}}) \) is the dominating predicate for \( \text{DEL}_F^{\text{crash}} \).

**Theorem 5.19** (\( f_{n-F} \) Dominates \( \text{DEL}_F^{\text{crash}} \)). \( f_{n-F} \) dominates \( \text{DEL}_F^{\text{crash}} \).

**Proof.** Let \( f \) be a valid strategy for \( \text{DEL}_F^{\text{crash}} \); the theorem follows by Definition 5.10 from proving that \( f \prec_{\text{DEL}_F^{\text{crash}}} f_{n-F} \) — that is \( \mathcal{HO}_{f_{n-F}}(\text{DEL}_F^{\text{crash}}) \subseteq \mathcal{HO}_{f}(\text{DEL}_F^{\text{crash}}) \).

Let \( ho \in \mathcal{HO}_{f_{n-F}}(\text{DEL}_F^{\text{crash}}) \), and let \( t \) be the canonical execution of \( ho \). Since \( \text{DEL}_F^{\text{crash}} \) contains the total collection, \( t \) is an execution of \( \text{DEL}_F^{\text{crash}} \) by Lemma 5.14. We need to prove that it is also an execution of \( f \) to conclude by Lemma 5.15 that \( f \) generates \( ho \), and thus that the inequality above and the theorem hold. We do so by contradiction. Assume \( t \) is not an execution of \( f \). By Definition 5.6, it is either because the fairness condition is broken or because some \( \text{next}_p \) for some process \( p \) happens when the local state of \( p \) is not in \( f \). Since Definition 5.13 of canonical executions implies that \( t \) contains an infinite number of \( \text{next}_p \) for every process \( p \in \Pi \), the problem must come from some \( \text{next}_j \) done by a process \( j \) when \( j \)'s local state is not in \( f \). Let \( r \) be the first round where this happens. At the point of the forbidden \( \text{next}_j \), by Definition 5.13 of a canonical execution, \( j \) has received all the messages from previous rounds, and all the messages from \( ho(r,j) \). Then \( ho \in \mathcal{HO}_{f_{n-F}}(\text{DEL}_F^{\text{crash}}) \) implies that \( ho \in \mathcal{HO}_F \) by Theorem 5.18. It then follows from the definition of \( \mathcal{HO}_F \) that \( ho(r,j) \) contains at least \( n - F \) processes.

We define \( c_{\text{block}} \) such that:

\[
\forall r' > 0, \forall k \in \Pi : c_{\text{block}}(r', k) \triangleq \begin{cases} 
\Pi & \text{if } r' < r \\
ho(r,j) & \text{otherwise}
\end{cases}
\]

This corresponds to the collection where all the processes from which \( j \) did not receive a message at the problematic \( \text{next}_j \) in \( t \) are correct up to round \( r \) and then stop sending messages. \( c_{\text{block}} \) is a delivered collection of \( \text{DEL}_F^{\text{crash}} \) by Definition 3.2: processes that stop sending messages never do again, and at most \( F \) processes do so because \( ho(r,j) \) contains at least \( n - F \) processes by the reasoning above.

Let \( t' = st(f, c_{\text{block}}) \) be the standard execution of \( f \) on \( c_{\text{block}} \). Lemma 5.12 entails that \( t' \) is an execution of \( f \) on \( c_{\text{block}} \). Since \( r \) is the smallest round in \( t \) with a wrong \( \text{next}_j \), for all rounds \( r < r \) the local state of \( j \) is enough for \( f \) to allow the change of round. By Definition 5.11 of standard executions, all \( \text{ch}ange_{sk} \) for \( k < r \) contain a next transition for all processes in \( t' \). By the same definition, all \( \text{del}_{sk} \) for \( k \leq r \) of \( t' \) contain the same deliveries for each process as the deliveries for \( j \) in the \( \text{del}_{sk} \) of \( t \). Hence, in \( t' \), all the processes reach round \( r \), all get the same state as \( j \) in \( t \) at round \( r \), and thus they all block at this round, which means the suffix of \( t' \) is made of \( \text{stop} \) only. \( t' \) is invalid, and so is \( f \). This contradicts the hypothesis that \( f \) is valid; we conclude that \( ho \in \mathcal{HO}_f(\text{DEL}_F^{\text{crash}}) \). Therefore, \( f_{n-F} \) dominates \( f \) by Definition 5.10, where \( f \) is any valid strategy for \( \text{DEL}_F^{\text{crash}} \), which means that \( f_{n-F} \) dominates \( \text{DEL}_F^{\text{crash}} \) by Definition 5.10. \( \square \)

Waiting for \( n - f \) messages thus gives us the best heard-of predicate that can be implemented on \( \text{DEL}_F^{\text{crash}} \). This means that there is no point in remembering messages from past rounds, and messages from future rounds are not used either. Intuitively, messages from past rounds are of no use in detecting crashes in the current round. As for messages from
future rounds, they actually serve to detect that a process has not crashed when sending its messages from the current round. For this to actually change the heard-of predicate, it would require that some heard-of collection be impossible to generate when using this future information. This is not the case, as there is always an execution where no message from future rounds are delivered early (the canonical execution).

6. Oblivious Strategies: Looking Only at the Current Round

Because of the generality of strategies, considering them all brings many issues in proving domination. Yet there exist interesting classes of strategies on which results can be derived. Our first such class is the class of oblivious strategies: they depend only on the received messages from the current round. For example, \( f_{n-F} \) is an oblivious strategy, as it counts messages from the current round. Despite their apparent simplicity, some oblivious strategies dominate non-trivial delivered predicates, as in the case of \( f_{n-F} \) and \( \text{DEL}_F^{\text{crash}} \).

In this section, we define oblivious strategies and give a necessary and sufficient condition for an oblivious strategy to be valid (Section 6.1). This yields useful results on the composition of oblivious strategies (Section 6.2), and enables to compute the heard-of predicate of an oblivious strategy applied to a delivered predicate (Section 6.3). Finally, we give a sufficient condition for oblivious domination, and show that this condition is preserved by composition (Section 6.4).

6.1. Definition and Expressiveness. Oblivious strategies are a family of strategies in the sense of Definition 5.5 — where the equivalence relation between the local states compare only the messages received for the current round.

**Definition 6.1 (Oblivious Strategies and \( \text{Nexts}_f \)).** Let \( \text{obliv} \) be the function such that \( \forall q \in Q : \text{obliv}(q) \triangleq \{k \in \Pi \mid (q.\text{round}, k) \in q.\text{mes}\} \). Let \( \approx_{\text{obliv}} \) the equivalence relation defined by \( q_1 \approx_{\text{obliv}} q_2 \) iff \( \text{obliv}(q_1) = \text{obliv}(q_2) \). The family of oblivious strategies is \( \text{family}(\approx_{\text{obliv}}) \).

For \( f \) an oblivious strategy, let \( \text{Nexts}_f \triangleq \{\text{obliv}(q) \mid q \in f\} \). It uniquely defines \( f \).

An oblivious strategy reduces to a collection of sets, the sets of processes from which receiving a message in the current round is enough to change round. The strategy allows the change of round if, and only if, the processes heard at the current round form a set in this collection. This provides a simple necessary condition on such a strategy \( f \) to be valid: its \( \text{Nexts}_f \) set must contain all the delivered sets from the corresponding delivered predicate. If it does not, an execution would exist where the messages received at some round \( r \) by some process \( p \) are exactly this delivered set, which would block forever the process \( p \) and make the strategy invalid. This necessary condition also proves sufficient.

**Lemma 6.2 (Necessary and Sufficient Condition for Validity of an Oblivious Strategy).** Let \( \text{DEL} \) be a delivered predicate and \( f \) be an oblivious strategy. Then \( f \) is valid for \( \text{DEL} \iff f \supseteq \{q \mid \exists c \in \text{DEL}, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p)\} \).

**Proof.**

- \( (\Rightarrow) \) Let \( f \) be valid for \( \text{DEL} \). We show by contradiction that \( f \) contains all local states \( q \) such that \( \exists c \in \text{DEL}, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p) \). Assume there is some \( q_{\text{block}} \) for which it is not the case: then \( \exists c \in \text{DEL}, r > 0 \) and \( j \in \Pi \) such that \( \text{obliv}(q_{\text{block}}) = c(r, j) \) and \( q_{\text{block}} \notin f \). By Definition 6.1, this means that for every \( q \) such that \( \text{obliv}(q) = \text{obliv}(q_{\text{block}}) = c(r, j) \),
we have \( q \not\in f \). Let \( t = st(f, c) \) be the standard execution of \( f \) on \( c \). This is an execution of \( f \) on \( c \) by Lemma 5.12. The sought contradiction is reached by proving that \( t \) is invalid. To do so, we split according to two cases: the first case is where there is a blocking process before round \( r \), and the second case is where there is no blocking process before round \( r \). This last case then uses the hypothesis on \( c(r, j) \) to show that all the processes block at \( r \).

- During one of the first \( r - 1 \) iterations of \( t \), there is some process which cannot change round. Let \( r' \) be the smallest iteration where it happens, and \( k \) be a process unable to change round at the \( r' \)-th iteration. By minimality of \( r' \), all the processes arrive at round \( r' \) in \( t \); by Definition 5.11 of the standard execution, all messages for \( k \) from round \( r' \) are delivered before the \( \text{change}_r \) part of the iteration. Let \( q \) be the local state of \( k \) at the start of \( \text{change}_r \) in the \( r' \)-th iteration, and let \( q' \) be any local state of \( k \) afterward. The above tells us that as long as \( q'.\text{round} = q.\text{round} \), we have \( \text{obliv}(q) = \text{obliv}(q') \) and thus \( q' \not\in f \). Therefore, \( k \) can never change round while at round \( r' \). We conclude that \( t \) is invalid by Definition 5.17.

- For the first \( r - 1 \) iterations, all the processes change round. Thus everyone arrives at round \( r \) in the \( r - 1 \)-th iteration. By Definition 5.11 of the standard execution, all messages from the round are delivered before the \( \text{change}_r \) part of the \( r \)-th iteration. Thus \( j \) is in a local state \( q \) at the \( \text{change}_r \) part of the \( r \)-th iteration such that \( \text{obliv}(q) = c(r, j) = \text{obliv}(q_{\text{block}}) \). By hypothesis, this means \( q \not\in f \) and thus that \( j \) cannot change round. Let \( q' \) be any local state of \( j \) afterward. The above tells us that as long as \( q'.\text{round} = r \), we have \( \text{obliv}(q) = \text{obliv}(q') = c(r, j) \) and thus \( q' \not\in f \). Therefore, \( j \) can never change round while at round \( r \). Here too, \( t \) is invalid by Definition 5.17.

Either way, we reach a contradiction with the validity of \( f \). Therefore \( f \supseteq \{ q | \exists c \in \text{DEL}, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p) \} \).

- \((\Leftarrow)\) Let \( \text{DEL} \) and \( f \) be such that \( f \supseteq \{ q | \exists c \in \text{DEL}, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p) \} \). We show by contradiction that \( f \) is valid. Assume the contrary: there is some \( t \in \text{execs}_f(\text{DEL}) \) which is invalid. By Definition 5.17 of validity, there are some processes blocked at a round forever in \( t \). Let \( r \) be the smallest such round, and \( j \) be a process blocked at round \( r \) in \( t \). By minimality of \( r \), all the processes arrive at round \( r \). By Definition 5.2 of an execution of \( \text{DEL} \), there is a \( c \in \text{DEL} \) such that \( t \) is an execution of \( c \). This means by Definition 5.2 of an execution of a collection that all the messages from \( c(r, j) \) are eventually delivered. From this point on, every local state \( q \) of \( j \) satisfies \( \text{obliv}(q) = c(r, j) \); thus we have \( q \in f \) by hypothesis on \( f \). Then the fairness condition of executions of \( f \) from Definition 5.6 imposes that \( j \) does change round at some point. We conclude that \( j \) is not blocked at round \( r \) in \( t \), which contradicts the hypothesis that it is blocked forever at round \( r \) in \( t \).

When taking the oblivious strategy satisfying exactly this condition for validity, it results in a strategy dominating the other oblivious ones. It follows from the fact that this strategy waits for the minimum sets required to be valid, hence the name of minimal oblivious strategy.

**Definition 6.3** (Minimal Oblivious Strategy). Let \( \text{DEL} \) be a delivered predicate. The **minimal oblivious strategy** for \( \text{DEL} \) is \( f_{\text{min}} \triangleq \{ q | \exists c \in \text{DEL}, \exists p \in \Pi, \forall r > 0 : \text{obliv}(q) = c(r, p) \} \).

**Lemma 6.4** (Domination of Minimal Oblivious Strategy). Let \( \text{DEL} \) be a delivered predicate and \( f_{\text{min}} \) be its minimal oblivious strategy. Then \( f_{\text{min}} \) is a dominating oblivious strategy for \( \text{DEL} \).
Proof. First, $f_{\text{min}}$ is valid for $\text{DEL}$ by application of Lemma 6.2. Next, we take another oblivious strategy $f$, which is valid for $\text{DEL}$. Lemma 6.2 now gives us that $f_{\text{min}} \subseteq f$. When $f_{\text{min}}$ allows a change of round, so does $f$. This entails by Definition 5.6 that all executions of $f_{\text{min}}$ on $\text{DEL}$ are also executions of $f$ on $\text{DEL}$, and thus by Definition 5.9 that $\mathcal{HO}(f_{\text{min}}(\text{DEL})) \subseteq \mathcal{HO}(f(\text{DEL}))$. We conclude from Definition 5.10 that $f_{\text{min}}$ dominates any valid oblivious strategy for $\text{DEL}$.

These theorems guarantee that every delivered predicate has a strategy dominating the oblivious ones, by giving a means to build it. Of course, a formal definition is not the same as a constructive definition, which motivates the study of minimal strategies through the operations, and their relations to the operations on the corresponding predicates.

6.2. Composition of Oblivious Strategies. One fundamental property of minimal oblivious strategies is their nice behaviour under the proposed operations (union, combination, succession and repetition). That is, they give minimal oblivious strategies of resulting delivered predicates. Although this holds for all operations, succession and repetition are not useful here, as the succession of two minimal oblivious strategies is equal to their union, and the repetition of a minimal oblivious strategy is equal to the strategy itself. The first operation to study is therefore union. The minimal oblivious strategy of $\text{DEL}_1 \cup \text{DEL}_2$ and $\text{DEL}_1 \leadsto \text{DEL}_2$ is the same, as shown in the next theorem, and thus it’s the union of the minimal oblivious strategies of $\text{DEL}_1$ and $\text{DEL}_2$.

**Theorem 6.5 (Minimal Oblivious Strategy for Union and Succession).** Let $\text{DEL}_1, \text{DEL}_2$ be two delivered predicates, $f_1$ and $f_2$ the minimal oblivious strategies for, respectively, $\text{DEL}_1$ and $\text{DEL}_2$. Then $f_1 \cup f_2$ is the minimal oblivious strategy for $\text{DEL}_1 \cup \text{DEL}_2$ and $\text{DEL}_1 \leadsto \text{DEL}_2$.

**Proof idea.** Structurally, every proof in this subsection amounts to showing equality between the strategies resulting from the operations and the minimal oblivious strategy for the delivered predicate. For a union, the messages that can be received at each round are the messages that can be received at each round in the first predicate or in the second. This is also true for succession. Given that $f_1$ and $f_2$ are the minimal oblivious strategies of $\text{DEL}_1$ and $\text{DEL}_2$, they accept exactly the states where the messages received from the current round are in a delivered set of $\text{DEL}_1$ or a delivered set of $\text{DEL}_2$. Thus $f_1 \cup f_2$ is the minimal oblivious strategy for $\text{DEL}_1 \cup \text{DEL}_2$ and $\text{DEL}_1 \leadsto \text{DEL}_2$.

**Proof.** We first show that the minimal oblivious strategies of $\text{DEL}_1 \cup \text{DEL}_2$ and $\text{DEL}_1 \leadsto \text{DEL}_2$ are equal. By Definition 5.8, we need to prove that \( \{q \mid \exists c \in \text{DEL}_1 \cup \text{DEL}_2, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p)\} \subseteq \{q \mid \exists c \in \text{DEL}_1 \text{ DEL}_2, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p)\} \).

- Let \( q \) be such that $\exists c \in \text{DEL}_1 \cup \text{DEL}_2, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p)$.
  - If $c \in \text{DEL}_1$, then we take $c_2 \in \text{DEL}_2$, and take $c' = c[1, r], c_2$. Since by Definition 4.1 $c' \leadsto c_2$, we have $c' \in \text{DEL}_1 \leadsto \text{DEL}_2$. By definition of $c'$, $c'(r, p) = c(r, p)$; $r$ and $p$ showing that $\text{obliv}(q) = c'(r, p)$, and thus $q$ is in the set on the right.
  - If $c \in \text{DEL}_2$, then $c \in \text{DEL}_1 \leadsto \text{DEL}_2$ by Definition 4.1. We thus have $c, r$ and $p$ showing that $\text{obliv}(q) = c(r, p)$, and thus $q$ is in the set on the right.

- Let $q$ be such that $\exists c \in \text{DEL}_1 \text{ DEL}_2, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p)$.
  - If $c \in \text{DEL}_2$, then $c \in \text{DEL}_1 \cup \text{DEL}_2$ by Definition 4.1. We thus have $c, p$ and $r$ showing that $\text{obliv}(q) = c(r, p)$, and thus $q$ is in the set on the left.
  - If $c \notin \text{DEL}_2$, there exist $c_1 \in \text{DEL}_1, c_2 \in \text{DEL}_2$ and $r' > 0$ such that $c = c_1[1, r'], c_2$ by Definition 4.1.
Theorem 6.6

The predicate over processes and over rounds. This means that for any delivered set predicate, happens in the combination of predicates, we add an assumption: the symmetry of and thus never appear in the combination of collections. That these two delivered sets used in the intersection above never happen at the same round, the first state and the delivered set of received messages from the current round in the second state. Yet when taking the combination of two predicates, maybe the collections are such that these two delivered sets used in the intersection above never happen at the same round, and thus never appear in the combination of collections. Theorem 6.6 (Minimal Oblivious Strategy for Repetition). Let DEL be a delivered predicate, and f be its minimal oblivious strategy. Then f is the minimal oblivious strategy for DEL\omega.

Proof. We show that f = \{q | \exists c \in \text{DEL}\omega, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p)\}, which allows us to conclude by Definition 6.3 that f is the minimal oblivious strategy for DEL\omega.

Let q \in f. By minimality of f for DEL, \exists c \in \text{DEL}\omega, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p). We take c' \in \text{DEL}\omega such that c_1 = c and r_2 = r; the other c_i and r_i don’t matter for the proof. By Definition 4.1 of operations on predicates, and specifically repetition, we get c'(r, p) = c(r, p) = \text{obliv}(q). We have c', p and r showing that q is in the minimal oblivious strategy of DEL\omega.

(\supseteq) Let q be such that \exists c \in \text{DEL}\omega, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p). By Definition 4.1 of operations on predicates, and specifically repetition, there are c_i \in \text{DEL} and 0 < r_i < r_{i+1} such that r \in [r_i + 1, r_{i+1}] and c(r, p) = c_i(r - r_i, p). We have found c_i, p and (r - r_i) showing that q is in the minimal oblivious strategy for DEL. Since f is the minimal oblivious strategy for DEL, we get q \in f.

Combination is different from the other operations, as combining collections is done round by round. Since oblivious strategies do not depend on the round, the combination of two oblivious strategies will accept the combination of any two states accepted, that is, it will accept any intersection of the delivered set of received messages from the current round in the first state and the delivered set of received messages from the current round in the second state. Yet when taking the combination of two predicates, maybe the collections are such that these two delivered sets used in the intersection above never happen at the same round, and thus never appear in the combination of collections.

To ensure that every intersection of pairs of delivered sets, one from a collection from each predicate, happens in the combination of predicates, we add an assumption: the symmetry of the predicate over processes and over rounds. This means that for any delivered set D of the
symmetric delivered predicates, which allows us to apply Lemma 6.3 to show that

\section*{Proof idea.}

• This strategy: the smallest predicate (all its collections are contained in the other predicates) oblivious strategy has been computed, the next step is to extract the heard-of predicate for Computing Heard-Of Predicates of Oblivious Strategies.

known minimal oblivious strategies, the minimal oblivious strategy of the result can be

\section*{Theorem 6.8 (Minimal Oblivious Strategy for Combination).}

Let \( \text{DEL}_1, \text{DEL}_2 \) be two round symmetric delivered predicates, \( f_1 \) and \( f_2 \) the minimal oblivious strategies for, respectively, \( \text{DEL}_1 \) and \( \text{DEL}_2 \). Then \( f_1 \otimes f_2 \) is the minimal oblivious strategy for \( \text{DEL}_1 \otimes \text{DEL}_2 \).

\section*{Proof.}

We show that \( f_1 \otimes f_2 = \{ q \mid \exists r \in \text{DEL}_1 \otimes \text{DEL}_2, \exists p \in \Pi, \exists r > 0 : \text{obliv}(q) = c(r, p) \} \), which allows us to apply Lemma 6.3 to show that \( f_1 \otimes f_2 \) is the minimal oblivious strategy of \( \text{DEL}_1 \otimes \text{DEL}_2 \).

\section*{Definition 6.7 (Round Symmetric \( \text{DEL} \)).}

Let \( \text{DEL} \) be a delivered predicate. \( \text{DEL} \) is round symmetric iff \( \forall c \in \text{DEL}, \forall r > 0, \forall k \in \Pi, \forall r' > 0, \forall k \in \Pi, \exists c' \in \text{DEL} : c(r, k) = c'(r', j) \).

\section*{Definition 6.9 (Heard-Of Product).}

Let \( S \subseteq \mathcal{P} (\Pi) \). The heard-of product generated by \( S \), \( \text{HOProd}(S) \triangleq \{ h, \text{a heard-of collection} \mid \forall p \in \Pi, \forall r > 0 : h(r, p) \in S \} \).
Here is the intuition: defining a heard-of collection requires, for each round and each process, the corresponding heard-of set. A heard-of product is then the set of all collections that have heard-of sets from the set given as argument. So the total heard-of predicate (containing only the total collection) is the heard-of product of the set $\Pi$. And $\mathcal{HO}_F$ is the heard-of product of all subsets of $\Pi$ of size $\geq n - F$.

The following lemma links the $\text{Nexts}_f$ of some valid oblivious strategy and the heard-of predicate for this strategy: the predicate is the heard-of product of the $\text{Nexts}_f$.

**Lemma 6.10 (Heard-Of Predicate of an Oblivious Strategy).** Let $\text{DEL}$ be a delivered predicate containing $c_{\text{total}}$ and let $f$ be a valid oblivious strategy for $\text{DEL}$. Then $\mathcal{HO}_f(\text{DEL}) = \mathcal{HOProd}(\text{Nexts}_f)$.

**Proof.**

- $(\subseteq)$ To prove this first direction, we show that the heard-of sets of any collection in $\mathcal{HO}_f(\text{DEL})$ are in $\text{Nexts}_f$. This then entails that $\mathcal{HO}_f(\text{DEL}) \subseteq \mathcal{HOProd}(\text{Nexts}_f)$. By Definition 5.9 of the heard-of collection of an execution, every heard-of set contains the set of messages from the current round that was already received at the $\text{next}_p$ transition where the process $p$ changed round. By Definition 5.6 of the executions of a strategy, such a $\text{next}_p$ transition can only happen if the local state of the process $p$ is in $f$. By Definition 6.1 of oblivious strategies, $f$ contains exactly the states such that the messages received from the current round form a set in $\text{Nexts}_f$. Therefore, the heard-of set of any collection generated by $f$ on a collection of $\text{DEL}$ are necessarily in $\text{Nexts}_f$.

- $(\supseteq)$ Let $ho$ be a heard-of collection such that $\forall r > 0, \forall j \in \Pi : ho(r, j) \in \text{Nexts}_f$. Let $t$ be the canonical execution of $ho$. It is an execution by Lemma 5.14. By Definition 5.13, at each round, processes receive a set of messages in $\text{Nexts}_f$. By Definition 6.1 of oblivious strategies, this entails that the local states are in $f$ when the processes change rounds. And so, by Definition 5.6, it is an execution of $f$. Hence $t$ is an execution of $f$ on $\text{DEL}$, because $\text{DEL}$ contains the total predicate. Since $t = \text{can}(ho)$, Lemma 5.15 implies that $h_t = ho$. We conclude that $ho \in \mathcal{HO}_f(\text{DEL})$.

Thanks to this characterization, the heard-of predicate generated by the minimal strategies for the operations is computed in terms of the heard-of predicate generated by the original minimal strategies.

**Theorem 6.11 (Heard-Of Predicate of Minimal Oblivious Strategies).** Let $\text{DEL}, \text{DEL}_1, \text{DEL}_2$ be delivered predicates containing $c_{\text{total}}$. Let $f, f_1, f_2$ be their respective minimal oblivious strategies. Then:

- $\mathcal{HO}_{f_1 \cup f_2}(\text{DEL}_1 \cup \text{DEL}_2) = \mathcal{HO}_{f_1 \cup f_2}(\text{DEL}_1 \leadsto \text{DEL}_2) = \mathcal{HOProd}(\text{Nexts}_{f_1} \cup \text{Nexts}_{f_2})$.
- If $\text{DEL}_1$ or $\text{DEL}_2$ are round symmetric, then:
  - $\mathcal{HO}_{f_1 \otimes f_2}(\text{DEL}_1 \otimes \text{DEL}_2) = \mathcal{HOProd}(\{ n_1 \cap n_2 \mid n_1 \in \text{Nexts}_{f_1} \wedge n_2 \in \text{Nexts}_{f_2} \})$.
  - $\mathcal{HO}_{f}(\text{DEL}^\omega) = \mathcal{HO}_f(\text{DEL})$.

**Proof.** Obviously, we want to apply Lemma 6.10. Then we first need to show that the delivered predicates contain $c_{\text{total}}$.

- By hypothesis, $\text{DEL}_1$ and $\text{DEL}_2$ contain $c_{\text{total}}$. Then $\text{DEL}_1 \cup \text{DEL}_2$ trivially contains it too by Definition 4.1 of operations on predicates.

- By hypothesis, $\text{DEL}_1$ and $\text{DEL}_2$ contain $c_{\text{total}}$. Then $\text{DEL}_1 \otimes \text{DEL}_2$ contains $c_{\text{total}} \otimes c_{\text{total}} = c_{\text{total}}$ by Definition 4.1 of operations on predicates.
• By hypothesis, \( \text{DEL}_1 \) and \( \text{DEL}_2 \) contain \( c_{\text{total}} \). Then \( \text{DEL}_1 \bowtie \text{DEL}_2 \supseteq \text{DEL}_2 \) contains it too by Definition 4.1 of operations on predicates.

• By hypothesis, \( \text{DEL} \) contains \( c_{\text{total}} \). We can recreate \( c_{\text{total}} \) by taking all \( c_i = c_{\text{total}} \) and whichever \( r_i \). Thus \( \text{DEL}^v \) contains \( c_{\text{total}} \) by Definition 4.1 of operations on predicates.

Next, the strategies \( f_1 \cup f_2 \), \( f_1 \otimes f_2 \) and \( f \) are the respective minimal oblivious strategies by Theorem 6.5, Theorem 6.8 and Theorem 6.6. They are also valid by Theorem 6.2.

Lastly, we need to show that the \( \text{Nexts}_f \) for the strategies corresponds to the generating sets in the theorem.

• We show \( \text{Nexts}_{f_1 \cup f_2} = \text{Nexts}_{f_1} \cup \text{Nexts}_{f_2} \), and thus that

\[
\text{HOProd}(\text{Nexts}_{f_1 \cup f_2}) = \text{HOProd}(\text{Nexts}_{f_1} \cup \text{Nexts}_{f_2}).
\]

- \( (\subseteq) \) Let \( n \in \text{Nexts}_{f_1 \cup f_2} \). Then \( \exists q \in f_1 \cup f_2 : \text{obliv}(q) = n \). By Definition 4.1 of operations on predicates, and specifically union, \( q \in f_1 \) or \( q \in f_2 \). We fix \( q \in f_1 \) (the case \( q \in f_2 \) is symmetric). Then \( n \in \text{Nexts}_{f_1} \) by Definition 6.1 of oblivious strategies. We conclude that \( n \in \text{Nexts}_{f_1} \cup \text{Nexts}_{f_2} \).

- \( (\supseteq) \) Let \( n \in \text{Nexts}_{f_1} \cup \text{Nexts}_{f_2} \). We fix \( n \in \text{Nexts}_{f_1} \) (as always, the other case is symmetric). Then \( \exists q \in f_1 : \text{obliv}(q) = n \). As \( q \in f_1 \) implies \( q \in f_1 \cup f_2 \), we conclude that \( n \in \text{Nexts}_{f_1 \cup f_2} \).

• We show \( \text{Nexts}_{f_1 \otimes f_2} = \{ n_1 \cap n_2 \mid n_1 \in \text{Nexts}_{f_1} \land n_2 \in \text{Nexts}_{f_2} \} \), and thus that

\[
\text{HOProd}(\text{Nexts}_{f_1 \otimes f_2}) = \text{HOProd}(\{ n_1 \cap n_2 \mid n_1 \in \text{Nexts}_{f_1} \land n_2 \in \text{Nexts}_{f_2} \}).
\]

- \( (\subseteq) \) Let \( n \in \text{Nexts}_{f_1 \otimes f_2} \). Then \( \exists q \in f_1 \otimes f_2 : \text{obliv}(q) = n \). By Definition 4.1 of operations on predicates, and specifically of combination, \( \exists q_1 \in f_1, \exists q_2 \in f_2 : q_1.\text{round} = q_2.\text{round} = q.\text{round} \land q = q_1 \otimes q_2 \). This means \( n = \text{obliv}(q) = \text{obliv}(q_1) \cap \text{obliv}(q_2) \). We conclude that \( n \in \{ n_1 \cap n_2 \mid n_1 \in \text{Nexts}_{f_1} \land n_2 \in \text{Nexts}_{f_2} \} \) by Definition 6.1 of oblivious strategies.

- \( (\supseteq) \) Let \( n \in \{ n_1 \cap n_2 \mid n_1 \in \text{Nexts}_{f_1} \land n_2 \in \text{Nexts}_{f_2} \} \). Then \( \exists n_1 \in \text{Nexts}_{f_1}, \exists n_2 \in \text{Nexts}_{f_2} : n = n_1 \cap n_2 \). By Definition 6.1 of oblivious strategies, and because \( f_1 \) and \( f_2 \) are oblivious strategies, we can find \( q_1 \in f_1 \) such that \( \text{obliv}(q_1) = n_1, q_2 \in f_2 \) such that \( \text{obliv}(q_2) = n_2 \), and \( q.\text{round} = q_2.\text{round} \). Then \( q = q_1 \otimes q_2 \) is a state of \( f_1 \otimes f_2 \). We have \( \text{obliv}(q) = n_1 \cap n_2 = n \). We conclude that \( n \in \text{Nexts}_{f_1 \otimes f_2} \) by Definition 6.1 of oblivious strategies.

• Trivially, \( \text{Nexts}_f = \text{Nexts}_f \).

6.4. Domination by Oblivious Strategies. Finally, the value of oblivious strategies depends on which delivered predicates have a dominating oblivious strategy. \( \text{DEL}_F^{\text{cash}} \) does, with the strategy \( f_{n-F} \). We consider delivered predicates that satisfy the so-called common round property. This condition captures the fact that given any delivered set \( D \), one can build, for any \( r > 0 \), a delivered collection where processes receive all the messages up to round \( r \), and then they share \( D \) as their delivered set in round \( r \). As a limit case, the predicate also contains the total collection. This common round property is preserved by the composition operators, which allows to derive complex dominating oblivious strategies from simple ones.

Definition 6.12 (Common Round Property). Let \( \text{DEL} \) be a delivered predicate. \( \text{DEL} \) has the common round property \( \triangleleft \)

- (Total collection) \( \text{DEL} \) contains the total collection \( c_{\text{total}} \).
Theorem 6.13 (Sufficient Condition of Oblivious Domination). Let \( \text{DEL} \) be a delivered predicate satisfying the common round property. Then, there is an oblivious strategy that dominates \( \text{DEL} \).

Proof. Let \( f_{\text{min}} \) be the minimal oblivious strategy for \( \text{DEL} \). It dominates the oblivious strategies for \( \text{DEL} \) by Lemma 6.4. We now prove that \( f_{\text{min}} \) dominates \( \text{DEL} \). This amount to showing that for \( f' \), a valid strategy for \( \text{DEL} \), we have \( f' \prec_{\text{DEL}} f_{\text{min}} \), that is \( \mathcal{HO}_{f_{\text{min}}}^{\text{DEL}} \subseteq \mathcal{HO}_{f'}^{\text{DEL}} \). Let \( ho \in \mathcal{HO}_{f_{\text{min}}}^{\text{DEL}} \) and \( t \) be the canonical execution of \( ho \). We show that \( t \) is an execution of \( f' \), which entails by Lemma 5.15 that \( ho \in \mathcal{HO}_{f'}^{\text{DEL}} \).

By Definition 6.12 of the common round property, \( \text{DEL} \) contains \( c_{\text{total}} \). By Lemma 5.14, \( t \) is an execution of \( c_{\text{total}} \), and thus an execution of \( f' \) on \( \text{DEL} \). Assume it is not. By Definition 5.6 of the executions of a strategy, the problem comes either from breaking fairness or from some \( \text{next}_j \) for some process \( j \) at a point where the local state of \( j \) is not in \( f' \). Since for every \( j \in \Pi : \text{next}_j \) happens an infinite number of times in \( t \) by Definition 5.13 of a canonical execution, the only possibility left is the second one: some \( \text{next}_j \) in \( t \) is done while the local state of \( j \) is not in \( f' \). There thus exists a smallest \( r \) such that some process \( j \) is not allowed by \( f' \) to change round when \( \text{next}_j \) is played at round \( r \) in \( t \).

Lemma 6.10 yields that \( \mathcal{HO}_{f_{\text{min}}}^{\text{DEL}} = \mathcal{HO}_{\Pi}^{\text{Prod}(N_{f_{\text{min}}})} \). By Definition 6.3 of minimal oblivious strategies, \( N_{f_{\text{min}}} = \{ c(r',p) \mid c \in \text{DEL} \land r' > 0 \land \exists \alpha \in \Pi : \alpha = r' \}. \) Thus \( \exists \alpha \in \text{DEL} : \exists r' > 0 \), \( \exists \alpha \in \Pi : ho(r,j) = c(r',p) \). Since \( \text{DEL} \) satisfies the common round property (Definition 6.12), it allows us to build \( c_{\text{block}} \) in \( \text{DEL} \) such that \( \forall r' < r, \exists k \in \Pi : c_{\text{block}}(r',k) = \Pi \land \forall k \in \Pi : c_{\text{block}}(r,k) = c(r',j) = ho(r,j) \). Finally, we build \( t_{\text{block}} = st(f',c_{\text{block}}) \) the standard execution of \( f' \) on \( c_{\text{block}} \). By Lemma 5.12, we know \( t_{\text{block}} \) is an execution of \( f' \) on \( c_{\text{block}} \). We then show that it is invalid by examining the two possibilities.

- During one of the first \( r - 1 \) iterations of \( t_{\text{block}} \), there is some process that cannot change round. Let \( r' \) be the smallest iteration where it happens, and \( k \) be a process unable to change round at the \( r' \)-th iteration. By minimality of \( r' \), all the processes arrive at round \( r' \), and by definition of \( c_{\text{block}} \) they all receive the same messages as \( k \) before \( \text{changes}_{r'} \). That means every process has the same local state as \( k \). Thus, all the processes are blocked at round \( r' \), there are no more round changes or deliveries, and \( t_{\text{block}} \) is invalid by Definition 5.17 of validity.

-
Theorem 6.14. Hence we show the invariance of the common round part. Thanks to Theorem 6.13, we have to show that the condition is maintained by the operations; the domination by an oblivious strategy directly follows from Theorem 6.13. The condition for \( DEL \) satisfying this condition will still be dominated by an oblivious strategy.

Either way, we deduce that \( f' \) is invalid, which is a contradiction. We conclude that \( t \) is an execution of \( f' \) on \( DEL \). Lemma 5.15 therefore implies that \( ho \in \mathcal{HO}_f(DEL) \). This entails that \( \mathcal{HO}_{f_{\min}}(DEL) \subseteq \mathcal{HO}_{f'}(DEL) \), and thus that \( f' \prec_{DEL} f_{\min} \). We conclude that \( f_{\min} \) dominates \( DEL \) by Definition 5.10.

This condition is maintained by the operations. Hence any predicate built from ones satisfying this condition will still be dominated by an oblivious strategy.

**Theorem 6.14** (Domination by Oblivious for Operations). Let \( DEL, DEL_1, DEL_2 \) be delivered predicates satisfying the common round property. Then \( DEL_1 \cup DEL_2, DEL_1 \otimes DEL_2, DEL_1 \rightsquigarrow DEL_2, DEL_2 \) also satisfy the common round property.

**Proof.** Thanks to Theorem 6.13, we have to show that the condition is maintained by the operations; the domination by an oblivious strategy directly follows from Theorem 6.13. The fact that \( c_{\text{total}} \) is still in the results of the operations was already shown in the proof of Theorem 6.11. Hence we show the invariance of the common round part.

- Let \( c \in DEL_1 \cup DEL_2 \). Thus \( c \in DEL_1 \) or \( c \in DEL_2 \). We fix \( c \in DEL_1 \) (the other case is symmetric). Then for \( p \in \Pi, r > 0 \) and \( r' > 0 \), we get a \( c' \in DEL_1 \) satisfying the condition of Definition 6.12 by the hypothesis that \( DEL_1 \) satisfies the common round property. Since \( DEL_1 \subseteq DEL_1 \cup DEL_2 \), we get \( c' \in DEL_1 \cup DEL_2 \). We conclude that the condition still holds for \( DEL_1 \cup DEL_2 \).

- Let \( c \in DEL_1 \otimes DEL_2 \). Then \( \exists c_1 \in DEL_1, \exists c_2 \in DEL_2 : c = c_1 \otimes c_2 \). For \( p \in \Pi, r > 0 \) and \( r' > 0 \), our hypothesis on \( DEL_1 \) and \( DEL_2 \) ensures that there are \( c'_1 \in DEL_1 \) satisfying the condition of Definition 6.12 for \( c_1 \) and \( c'_2 \in DEL_2 \) satisfying the condition of Definition 6.12 for \( c_2 \). We argue that \( c' = c'_1 \otimes c'_2 \) satisfies the condition of Definition 6.12 for \( c \). Indeed, \( \forall r'' < r', \forall q \in \Pi : c(r'', q) = c'_1(r'', q) \otimes c'_2(r'', q) = \Pi \) and \( \forall q \in \Pi : c(r', q) = c'_1(r', q) \otimes c'_2(r', q) = c_1(r, p) \otimes c_2(r, p) = c(r, p) \). We conclude that the condition of Definition 6.12 still holds for \( DEL_1 \otimes DEL_2 \).

- Let \( c \in DEL_1 \rightsquigarrow DEL_2 \). Since \( c \in DEL_2 \) the condition of Definition 6.12 trivially holds by hypothesis, we study the case where succession actually happens. Hence \( \exists c_1 \in DEL_1, \exists c_2 \in DEL_2, \exists r_{\text{change}} > 0 : c = c_1[1, r_{\text{change}}]c_2 \). For \( p \in \Pi, r > 0 \) and \( r' > 0 \), we consider two cases.

  - if \( r \leq r_{\text{change}} \), then our hypothesis on \( DEL_1 \) ensures that there is \( c'_1 \in DEL_1 \) satisfying the condition of Definition 6.12 for \( c_1 \). We argue that \( c' = c'_1[1, r']c_2 \in DEL_1 \rightsquigarrow DEL_2 \) satisfies the condition of Definition 6.12 for \( c \). Indeed, \( \forall r'' < r', \forall q \in \Pi : c'(r'', q) = c'_1(r'', q) = \Pi \), and \( \forall q \in \Pi : c'(r', q) = c_1(r, p) = c(r, p) \).

  - if \( r > r_{\text{change}} \), then our hypothesis on \( DEL_2 \) ensures that there is \( c'_2 \in DEL_2 \) satisfying the condition of Definition 6.12 for \( c_2 \) at \( p \) and \( r - r_{\text{change}} \). That is, \( c'_2[1, r' - 1] = c_{\text{total}}[1, r' - 1] \land \forall q \in \Pi : c'_2(r', q) = c_2(r - r_{\text{change}}, p) \). We argue that \( c' = c'_2 \in DEL_1 \rightsquigarrow DEL_2 \) satisfies the condition of Definition 6.12 for \( c \). Indeed, \( \forall r'' < r', \forall q \in \Pi : c'_2(r'', q) = \Pi \), and \( \forall q \in \Pi : c'_2(r', q) = c_2(r - r_{\text{change}}, p) = c(r, p) \).
We conclude that the condition of Definition 6.12 still holds for \( \text{DE}l_1 \leadsto \text{DE}l_2 \).

- Let \( c \in \text{DE}l^\omega \). Let \((c_i)\) and \((r_i)\) be the collections and indices defining \( c \). We take \( p \in \Pi, r > 0 \) and \( r' > 0 \). Let \( i > 0 \) be the integer such that \( r \in [r_i + 1, r_i + 1] \). By hypothesis on \( \text{DE}l \), there is \( c'_i \in \text{DE}l \) satisfying the condition of Definition 6.12 for \( c_i \) at \( p \) and \( r - r_i \). That is, \( c_i'[1, r_i - 1] = c_{\text{total}}[1, r_i - 1] \land \forall q \in \Pi : c_i'(r_i, q) = c_i(r - r_i, p) \). We argue that \( c'_i \in \text{DE}l \) satisfies the condition of Definition 6.12 for \( c \). Indeed, \( \forall r'' \leq r', \forall q \in \Pi \), we have: \( c_i'(r'', q) = \Pi \) and \( \forall q \in \Pi : c_i'(r', q) = c_i(r - r_i, p) = c(r, p) \). We conclude that the condition of Definition 6.12 still holds for \( \text{DE}l^\omega \).

Therefore, as long as the initial building blocks satisfy the common round property, so do the results of the operations — and the latter is dominated by its minimal oblivious strategy, a strategy that can be computed easily from the results of this section.

### 7. Conservative Strategies: Looking at Present and Past Rounds

The class of considered strategies expands the class of oblivious strategies by considering past rounds and the round number in addition to the present round. This is a generalization of oblivious strategies that trades simplicity for expressivity, while retaining a nice structure.

The structure of this section is similar to the previous one: it defines conservative strategies and give a necessary and sufficient condition for a conservative strategy to be valid (Section 7.1), presents results on the composition of conservative strategies (Section 7.2) that enables to compute upper bounds on the heard-of predicates of conservative strategies (Section 7.3), and ends with a sufficient condition for conservative domination, condition preserved by composition (Section 7.4).

#### 7.1. Definition and Expressiveness

**Definition 7.1 (Conservative Strategy).** Let \( \text{cons} \) be the function such that

\[
\forall q \in Q, \ \text{cons}(q) \triangleq \langle q, \text{round}, \{ (r, k) \in q, \text{mes} | r \leq q, \text{round} \} \rangle.
\]

Let \( \approx_{\text{cons}} \) the equivalence relation defined by \( q_1 \approx_{\text{cons}} q_2 \) if \( \text{cons}(q_1) = \text{cons}(q_2) \). The family of conservative strategies is \( \text{fam}_{\text{ily}}(\approx_{\text{cons}}) \). We write \( \text{Nexts}_f^c \triangleq \{\text{cons}(q) | q \in f\} \) for the set of conservative states in \( f \). This uniquely defines \( f \).

In analogy with the case of oblivious strategies, there is an intuitive necessary and sufficient condition for such a strategy to be valid for a given delivered predicate.

**Lemma 7.2 (Necessary and Sufficient Condition for Validity of a Conservative Strategy).**

Let \( \text{DE}l \) be a delivered predicate and \( f \) be a conservative strategy. Then \( f \) is valid for \( \text{DE}l \) if and only if \( f \supseteq \{ q \in Q | \exists c \in \text{DE}l, \exists p \in \Pi, \forall r \leq q, \text{round} : q(r) = c(r, p) \} \).

**Proof.**

- \((\Rightarrow)\) Let \( f \) be valid for \( \text{DE}l \). We show by contradiction that it satisfies the right-hand side of the above equivalence. Assume there is \( g_{\text{block}} \) a local state such that \( \exists c \in \text{DE}l, \exists r > 0, \exists j \in \Pi : \text{cons}(g_{\text{block}}) = \langle r, \{ (r', k) | r' \leq r \land k \in c(r', j) \} \rangle \) and \( q \notin f \). By Definition 7.1, this means that for every \( q \) such that \( \text{cons}(q) = \text{cons}(g_{\text{block}}) = \langle r, \{ (r', k) | r' \leq r \land k \in c(r', j) \} \rangle \), \( q \notin f \). Let \( t = \text{st}(f, c) \) be the standard execution of \( f \) on \( c \). This is an execution of \( f \) on \( t \) by Lemma 5.12. The sought contradiction is reached by proving that \( t \) is invalid for \( \text{DE}l \), and thus \( f \) is invalid for \( \text{DE}l \) too. To do so, we split according to two cases: the first is the
case where there is a blocking process before round \( r \), and the other uses the hypothesis on the prefix of \( c \) for \( j \) up to round \( r \).

- During one of the first \( r - 1 \) iterations of \( t \), there is some process which cannot change round. Let \( r' \) be the smallest iteration of the canonical execution where it happens, and \( k \) be a process unable to change round at the \( r' \)-th iteration. By minimality of \( r' \), all the processes arrive at round \( r' \) in \( t \); by Definition 5.11 of the standard execution, all messages for \( k \) from all rounds up to \( r' \) are delivered before the \textit{change} part of the iteration. Let \( q \) the local state of \( k \) at the start of \textit{change}_{r'}, and let \( q' \) be any local state of \( k \) afterward. The above tells us that as long as \( q'.\text{round} = q.\text{round} \), we have \( \text{cons}(q) = \text{cons}(q') \) and thus \( q' \not\in f \). Therefore, \( k \) can never change round while at round \( r' \). We conclude that \( t \) is invalid for \( \text{DEL} \) by Definition 5.17.

- For the first \( r - 1 \) iterations, all the processes change round. Thus everyone arrives at round \( r \) in the \( r - 1 \)-th iteration. By Definition 5.11 of the standard execution, all messages from rounds up to \( r \) are delivered before the \textit{change} part of the \( r \)-th iteration. Thus \( j \) is in a local state \( q \) at the \textit{change}_r part of the \( r \)-th iteration such that \( \text{cons}(q) = \langle r, \{ (r', k) \mid r' \leq r \land k \in c(r', j) \} \rangle = \text{cons}(q') \). By hypothesis, this means \( q' \not\in f \) thus that \( j \) cannot change round. Let \( q' \) be any local state of \( j \) afterward. The above tells us that as long as \( q'.\text{round} = q.\text{round} \), we have \( \text{cons}(q) = \text{cons}(q') \) and thus \( q' \not\in f \). Therefore, \( j \) can never change round while at round \( r \). Here too, \( t \) is invalid for \( \text{DEL} \) by Definition 5.17.

Either way, we reach a \textbf{contradiction} with the validity of \( f \) for \( \text{DEL} \).

- \((\Leftarrow)\) Let \( \text{DEL} \) and \( f \) be such that \( \forall c \in \text{DEL}, \langle r, \{ (r', k) \mid r' \leq r \land k \in c(r', j) \} \rangle \in \text{Nexts}_C^f \). We show by contradiction that \( f \) is valid for \( \text{DEL} \). \textbf{Assume} the contrary: there is some \( t \in \text{execs}_f(\text{DEL}) \) that is invalid for \( \text{DEL} \). Thus there are some processes blocked at a round forever in \( t \). Let \( r \) be the smallest such round, and \( j \) be a process blocked at round \( r \) in \( t \). By minimality of \( r \), all the processes arrive at round \( r \). By Definition 5.2 of an execution of \( \text{DEL} \), there is a \( c \in \text{DEL} \) such that \( t \) is an execution of \( c \). This means by Definition 5.2 of an execution of a collection that all messages from all the delivered sets of \( j \) up to round \( r \) are eventually delivered. From this point on, every local state \( q \) of \( j \) satisfies \( \text{cons}(q) = \langle r, \{ (r', k) \mid r' \leq r \land k \in c(r', j) \} \rangle \); thus we have \( q \in f \) by hypothesis on \( f \). Then the fairness condition of executions of \( f \) from Definition 5.6 imposes that \( j \) does change round at some point. We conclude that \( j \) is not blocked at round \( r \) in \( t \), which \textbf{contradicts} the hypothesis that \( j \) is blocked forever at round \( r \) in \( t \).

The strategy satisfying exactly this condition is the minimal conservative strategy of \( \text{DEL} \), and it is a strategy dominating all the conservative strategies for this delivered predicate.

\begin{definition}[Minimal Conservative Strategy] \textbf{Definition 7.3} \( \textbf{(Minimal Conservative Strategy)} \). Let \( \text{DEL} \) be a delivered predicate. Then the \textbf{minimal conservative strategy} for \( \text{DEL} \) is \( f_{\text{min}} \triangleq \) the conservative strategy such that \( f = \{ q \in Q \mid \exists c \in \text{DEL}, \exists p \in \Pi, \forall r \leq q.\text{round} : q(r) = c(r, p) \} \).
\end{definition}

Intuitively, when every message from a prefix is delivered, there is no message left from past and present; a valid conservative strategy has to accept the state, or it would be blocked forever.

\begin{remark}[Prefix and conservative state of a prefix] \textbf{Remark 7.4} \( \textbf{(Prefix and conservative state of a prefix)} \). Intuitively, a prefix of a collection \( c \) for a process \( p \) at round \( r \) is the sequence of sets of messages received by \( p \) at rounds \( \leq r \) in \( c \). Then we can define a state corresponding to this prefix by fixing its round at \( r \) and
Lemma 7.5 (Domination of Minimal Conservative Strategy). Let $\text{DEL}$ be a delivered predicate and $f_{\text{min}}$ be its minimal conservative strategy. Then $f_{\text{min}}$ dominates the conservative strategies for $\text{DEL}$.

Proof. First, $f_{\text{min}}$ is valid for $\text{DEL}$ by application of Lemma 7.2. Next, we take another conservative strategy $f$, valid for $\text{DEL}$. Lemma 7.2 gives us that $f_{\text{min}} \subseteq f$. Hence, when $f_{\text{min}}$ allow a change of round, so does $f$. This entails by Definition 5.6 that all the executions of $f_{\text{min}}$ for $\text{DEL}$ are also executions of $f$ for $\text{DEL}$, and by Definition 5.9 that $\mathcal{HO}_{f_{\text{min}}}^{\text{DEL}} \subseteq \mathcal{HO}_f^{\text{DEL}}$. We conclude from Definition 5.10 that $f_{\text{min}}$ dominates any valid conservative strategy for $\text{DEL}$. \hfill $\square$

7.2. Composition of Conservative Strategies. Like oblivious strategies, applying operations to minimal conservative strategies gives the minimal conservative strategies of the predicates after the analogous operations.

Theorem 7.6 (Minimal Conservative Strategy for Union). Let $\text{DEL}_1, \text{DEL}_2$ be two delivered predicates, $f_1$ and $f_2$ the minimal conservative strategies for, respectively, $\text{DEL}_1$ and $\text{DEL}_2$. Then $f_1 \cup f_2$ is the minimal conservative strategy for $\text{DEL}_1 \cup \text{DEL}_2$.

Proof. We only have to show that $f_1 \cup f_2$ is equal to Definition 7.3.

• $(\supseteq)$ Let $q$ be a state such that $\exists c \in \text{DEL}_1 \cup \text{DEL}_2, \exists p \in \Pi$ such that $\forall r \leq q.\text{round} : q(r) = c(r, p)$. If $c \in \text{DEL}_1$, then $q \in f_1$, by Definition 7.3 of the minimal conservative strategy because $f_1$ is the minimal conservative strategy for $\text{DEL}_1$, and by application of Lemma 7.2. Thus $q \in f_1 \cup f_2$. If $c \in \text{DEL}_2$, the same reasoning applies with $f_2$ in place of $f_1$. We conclude that $q \in f_1 \cup f_2$.

• $(\subseteq)$ Let $q \in f_1 \cup f_2$. This means that $q \in f_1 \lor q \in f_2$. The case where it is in both can be reduced to any of the two. If $q \in f_1$, then by Definition 7.3 of the minimal conservative strategy and by minimality of $f_1$, $\exists c_1 \in \text{DEL}_1, \exists p_1 \in \Pi$ such that $\forall r \leq q.\text{round} : q(r) = c_1(r, p_1)$. $\text{DEL}_1 \subseteq \text{DEL}_1 \cup \text{DEL}_2$, thus $c_1 \in \text{DEL}_1 \cup \text{DEL}_2$. We have found the $c$ and $p$ necessary to show $q$ is in the minimal conservative strategy for $\text{DEL}_1 \cup \text{DEL}_2$. If $q \in f_2$, the reasoning is similar to the previous case, replacing $f_1$ by $f_2$ and $\text{DEL}_1$ by $\text{DEL}_2$. \hfill $\square$

For the other three operations, slightly more structure is needed on the predicates. More precisely, they have to be independent of the processes. We require that any prefix of a process $k$ in a collection of the predicate is also the prefix of any other process $j$ in a possibly different collection of the same $\text{DEL}$. Hence the behaviors (fault, crashes, loss) are not targeting specific processes. This restriction fits the intuition behind many common fault models.

Definition 7.7 (Prefix Symmetric $\text{DEL}$). Let $\text{DEL}$ be a delivered predicate. $\text{DEL}$ is prefix symmetric if $\forall c \in \text{DEL}, \forall k \in \Pi, \forall r > 0, \forall j \in \Pi, \exists c' \in \text{DEL}, \forall r' \leq r : c'(r', k) = c(r', j).

This differs from the previous round symmetric $\text{DEL}$, in that here we focus on prefixes, while the other focused on rounds. Notice that none implies the other: round symmetry says nothing about the rest of the prefix, and prefix symmetry says nothing about the delivered sets when rounds are different. Assuming prefix symmetry, the conservation of the minimal conservative strategy by combination, succession and repetition follows.
Theorem 7.8 (Minimal Conservative Strategy for Combination). Let $\text{DEL}_1$, $\text{DEL}_2$ be two prefix symmetric delivered predicates, $f_1$ and $f_2$ the minimal conservative strategies for, respectively, $\text{DEL}_1$ and $\text{DEL}_2$. Then $f_1 \otimes f_2$ is the minimal conservative strategy for $\text{DEL}_1 \otimes \text{DEL}_2$.

Proof idea. Since $f_1$ and $f_2$ are the minimal conservative strategies of $\text{DEL}_1$ and $\text{DEL}_2$, $\text{Nexts}^C_{f_1}$ is the set of the conservative states of prefixes of $\text{DEL}_1$ and $\text{Nexts}^C_{f_2}$ is the set of the conservative states of prefixes of $\text{DEL}_2$. Also, the states accepted by $f_1 \otimes f_2$ are the combination of the states accepted by $f_1$ and the states accepted by $f_2$. The prefixes of $\text{DEL}_1 \otimes \text{DEL}_2$ are the prefixes of $\text{DEL}_1$ combined with the prefixes of $\text{DEL}_2$ for the same process. Thanks to prefix symmetry, we can take a prefix of $\text{DEL}_2$ and any process, and find a collection such that the process has that prefix. Therefore, the combined prefixes for the same process are the same as the combined prefixes of $\text{DEL}_1$ and $\text{DEL}_2$. Thus $\text{Nexts}^C_{f_1 \otimes f_2}$ is the set of conservative states of prefixes of $\text{DEL}_1 \otimes \text{DEL}_2$, and $f_1 \otimes f_2$ is its minimal conservative strategy.

Proof. We only need to show that $f_1 \otimes f_2$ is equal to Definition 7.3.

- $(\supseteq)$ Let $q$ be a state such that $\exists c \in \text{DEL}_1 \otimes \text{DEL}_2, \exists p \in \Pi$ such that $\forall r \leq q \text{.round} : q(r) = c(r, p)$. By definition of $c$, $\exists c_1 \in \text{DEL}_1, \exists c_2 \in \text{DEL}_2 : c_1 \otimes c_2 = c$. We take $q_1$ such that

$$q_1 \text{.round} = q \text{.round} \quad \text{and} \quad \forall r > 0 : \left( \begin{array}{ll} q_1(r) = c_1(r, p) & \text{if } r \leq q \text{.round} \\ q_1(r) = q(r) & \text{otherwise} \end{array} \right).$$

We also take $q_2$ such that

$$q_2 \text{.round} = q \text{.round} \quad \text{and} \quad \forall r > 0 : \left( \begin{array}{ll} q_2(r) = c_2(r, p) & \text{if } r \leq q \text{.round} \\ q_2(r) = q(r) & \text{otherwise} \end{array} \right).$$

First, $f_1$ and $f_2$ are valid for their respective predicates by Lemma 7.2 and Definition 7.3. Then by validity of $f_1$ and $f_2$ and by application of Lemma 7.2, we get $q_1 \in f_1$ and $q_2 \in f_2$. We also see that $q = q_1 \otimes q_2$. Indeed, for $r \leq q \text{.round}$, we have $q(r) = c(r, p) = c_1(r, p) \cap c_2(r, p) = q_1(r) \cap q_2(r)$; and for $r > q \text{.round}$, we have $q(r) = q(r) \cap q(r) = q_1(r) \cap q_2(r)$. Therefore $q \in \text{DEL}_1 \otimes \text{DEL}_2$.

- $(\subseteq)$ Let $q \in f_1 \otimes f_2$. By Definition 5.8 of operations on strategies, and specifically combination, $\exists q_1 \in f_1, \exists q_2 \in f_2$ such that $q_1 \text{.round} = q_2 \text{.round} = q \text{.round}$ and $q = q_1 \otimes q_2$. Since $f_1$ and $f_2$ are minimal conservative strategies of their respective DELs, by Definition 7.3 $\exists c_1 \in \text{DEL}_1, \exists p_1 \in \Pi$ such that $\forall r \leq q \text{.round} : q_1(r) = c_1(r, p_1)$; and $\exists c_2 \in \text{DEL}_2, \exists p_2 \in \Pi$ such that $\forall r \leq q \text{.round} : q_2(r) = c_2(r, p_2)$. By Definition 7.7 of prefix symmetry, the fact that $\text{DEL}_2$ is prefix symmetric implies that $\exists c \in \text{DEL}_2$ such that $\forall r \leq q \text{.round} : c_2(r, p_1) = c_2(r, p_2)$. Hence $\forall r \leq q \text{.round} : q_2(r) = c_2(r, p_1)$. By taking $c = c_1 \otimes c_2$, we get $\forall r \leq q \text{.round} : q(r) = q_1(r) \cap q_2(r) = c_1(r, p_1) \cap c_2(r, p_1) = c(r, p_1)$. We have found $c$ and $p$ showing that $q$ is in the minimal conservative strategy for $\text{DEL}_1 \otimes \text{DEL}_2$.

Theorem 7.9 (Minimal Conservative Strategy for Succession). Let $\text{DEL}_1, \text{DEL}_2$ be two prefix symmetric delivered predicates, $f_1$ and $f_2$ the minimal conservative strategies for, respectively, $\text{DEL}_1$ and $\text{DEL}_2$. Then $f_1 \rightsquigarrow f_2$ is the minimal conservative strategy for $\text{DEL}_1 \rightsquigarrow \text{DEL}_2$.

Proof idea. Since $f_1$ and $f_2$ are the minimal conservative strategies of $\text{DEL}_1$ and $\text{DEL}_2$, $\text{Nexts}^C_{f_1}$ is the set of the conservative states of prefixes of $\text{DEL}_1$ and $\text{Nexts}^C_{f_2}$ is the set of the conservative states of prefixes of $\text{DEL}_2$. Also, the states accepted by $f_1 \rightsquigarrow f_2$ are the succession of the states accepted by $f_1$ and the states accepted by $f_2$. The prefixes of $\text{DEL}_1 \rightsquigarrow \text{DEL}_2$ are the successions of prefixes of $\text{DEL}_1$ and prefixes of $\text{DEL}_2$ for the same process. Thanks to prefix symmetry, we can take a prefix of $\text{DEL}_2$ and any process, and find a collection such that the
process has that prefix. Therefore, the succession of prefixes for the same process are the same as the succession of prefixes of $\text{DEL}_1$ and $\text{DEL}_2$. Thus $\text{Nexts}_{f_1 \leadsto f_2}$ is the set of conservative states of prefixes of $\text{DEL}_1 \leadsto \text{DEL}_2$, and is its minimal conservative strategy. \hfill $\Box$

**Proof.** We only need to show that $f_1 \leadsto f_2$ is equal to Definition 7.3.

- $(\supseteq)$ Let $q$ be a state such that $\exists c \in \text{DEL}_1 \leadsto \text{DEL}_2, \exists p \in \Pi$ such that $\forall r' \leq q.\text{round} : q(r') = c(r', p)$. By Definition 4.1 of the operations on predicates, and specifically of succession, $\exists c_1 \in \text{DEL}_1, \exists c_2 \in \text{DEL}_2, \exists r > 0 : c = c_1[1, r].c_2$.

  - If $r = 0$, then $c[1, r] = c_2[1, r]$, and thus $\forall r' \leq q.\text{round} : q(r') = c_2(r', p)$. First, $f_2$ is valid for $\text{DEL}_2$ by Lemma 7.2 and Definition 7.3. Then the validity of $f_2$ and Lemma 7.2 allow us to conclude that $q \in f_2$ and thus that $q \in f_1 \leadsto f_2$.

  - If $r > 0$, we have two cases to consider.

    * If $q.\text{round} \leq r$, then $\forall r' \leq q.\text{round} : q(r') = c_1(r', p)$ $f_1$ is also valid for $\text{DEL}_1$ by Lemma 7.2 and Definition 7.3. We conclude by validity of $f_1$ and application of Lemma 7.2 that $q \in f_1$ and thus that $q \in f_1 \leadsto f_2$.

    * If $q.\text{round} > r$, then $c[1, q.\text{round}] = c_1[1, r].c_2[1, q.\text{round} - r]$. We take $q_1$ such that

$$q_1.\text{round} = r \quad \text{and} \quad \forall r' > 0 : \begin{cases} q_1(r') = c_1(r', p) & \text{if } r' \leq q_1.\text{round} \\ q_1(r') = q(r') & \text{otherwise} \end{cases},$$

and $q_2$ such that

$$q_2.\text{round} = q.\text{round} - r \quad \text{and} \quad \forall r' > 0 : \begin{cases} q_2(r') = c_2(r', p) & \text{if } r' \leq q_2.\text{round} \\ q_2(r') = q(r' - r) & \text{otherwise} \end{cases}.$$

Then by validity of $f_1$ and $f_2$ for their respective predicates, and by application of Lemma 7.2, we get $q_1 \in f_1$ and $q_2 \in f_2$.

We also have:

- $q_1.\text{round} + q_2.\text{round} = r + q.\text{round} - r = q.\text{round}$
- $\forall r' \leq q_1.\text{round} = r, q(r') = c(r', p) = c_1(r', p) = q_1(r')$
- $\forall r' \in [q_1.\text{round} + 1, q.\text{round}], q(r') = c(r', p) = c_2(r' - r, p) = q_2(r' - r) = q_2(r' - q_1.\text{round})$
- $\forall r' > q.\text{round}, q(r') = q_2(r' - r) = q_2(r' - q_1.\text{round})$

So Definition 5.8 gives $q = q_1 \leadsto q_2$.

We conclude that $q \in f_1 \leadsto f_2$.

- $(\subseteq)$ Let $q \in f_1 \leadsto f_2$. By Definition 5.8 of operations for strategies, specifically succession, there are three possibilities for $q$.

  - If $q \in f_1$, then by Definition 7.3 of the minimal conservative strategy and minimality of $f_1$ for $\text{DEL}_1$, we have $\exists c_1 \in \text{DEL}_1, \exists p_1 \in \Pi : \forall r \leq q.\text{round} : q(r) = c_1(r, p_1)$. Let $c_2 \in \text{DEL}_2$. We take $c = c_1[1, q.\text{round}].c_2$; we have $c \in c_1 \leadsto c_2$ by Definition 4.1 of operations for predicates. Then, $\forall r \leq q.\text{round} : q(r) = c_1(r, p_1) = c = c_1(r, p_1)$. We have found $c$ and $p$ showing that $q$ is in the minimal conservative strategy for $\text{DEL}_1 \leadsto \text{DEL}_2$ by Definition 7.3.

  - If $q \in f_2$, then by Definition 7.3 of the minimal conservative strategy and minimality of $f_2$ for $\text{DEL}_2$, we have $\exists c_2 \in \text{DEL}_2, \exists p_2 \in \Pi : \forall r \leq q.\text{round} : q(r) = c_2(r, p_2)$. As $\text{DEL}_2 \subseteq \text{DEL}_1 \leadsto \text{DEL}_2$ by Definition 4.1, thus $c_2 \in \text{DEL}_1 \leadsto \text{DEL}_2$. We have found $c$ and $p$ showing that $q$ is in the minimal conservative strategy for $\text{DEL}_1 \leadsto \text{DEL}_2$ by Definition 7.3.

  - There are $q_1 \in f_1$ and $q_2 \in f_2$ such that $q = q_1 \leadsto q_2$. Because $f_1$ and $f_2$ are the minimal conservative strategies of their respective $\text{DEL}$s, then by Definition 7.3 $\exists c_1 \in \text{DEL}_1, \exists p_1 \in \Pi$ such that $\forall r \leq q.\text{round} : q_1(r) = c_1(r, p_1)$; and $\exists c_2 \in \text{DEL}_2, \exists p_2 \in \Pi$
such that \( \forall r \leq q.round : q_2(r) = c_2(r, p_2) \). By Definition 7.7 of prefix symmetry, the fact \( \text{DEL}_2 \) is prefix symmetric implies that \( \exists c'_2 \in \text{DEL}_2 : \forall r \leq q.round : c'_2(r, p_1) = c_2(r, p_2) \). Hence \( \forall r \leq q.round : q_2(r) = c'_2(r, p_1) \). By taking \( c = c_1[1, q_1.round].c'_2 \), we have \( c \in c_1 \leadsto c'_2 \). Then \( \forall r \leq q.round = q_1.round + q_2.round \):

\[
\begin{align*}
q(r) &= q_1(r) \\
&= c_1(r, p_1) \\
&= c(r, p_1) \\
q(r) &= q_2(r - q_1.round) \\
&= c'_2(r - q_1.round, p_1) \\
&= c(r, p_1)
\end{align*}
\]

if \( r \leq q_1.round \),

\[
q(r) = q(r + \sum_{j \in [1,k-2]} q_1.round) \quad \text{if } r \in [q_1.round + 1, q_1.round + q_2.round]
\]

We have found \( c \) and \( p \) showing that \( q \) is in the minimal conservative strategy for \( \text{DEL}_1 \leadsto \text{DEL}_2 \) by Definition 7.3.

\[\square\]

**Theorem 7.10** (Minimal Conservative Strategy for Repetition). Let \( \text{DEL} \) be a prefix symmetric delivered predicate, and \( f \) be its minimal conservative strategy. Then \( f^* \) is the minimal conservative strategy for \( \text{DEL}^* \).

**Proof.** We only have to show that \( f^* \) is equal to Definition 7.3.

- \( (\supseteq) \) Let \( q \) be a state such that \( \exists c \in \text{DEL}^* \), \( \exists p \in \Pi \) such that \( \forall r \leq q.round : q(r) = c(r, p) \). By Definition 4.1 of operations for predicates, and specifically of repetition, \( \exists (c_i)_{i \in \mathbb{N}}, \exists (r_i)_{i \in \mathbb{N}*} \) such that \( r_1 = 0 \) and \( \forall i \in \mathbb{N}^* : (c_i \in \text{DEL} \land r_i < r_i + 1 \land c(r_i + 1, r_i + 1) = c_1[r_i + 1, r_i + 1 - r_i]) \). Let \( k \) be the biggest integer such that \( r_k \leq q.round \). We consider two cases.

  - If \( r_k = q.round \), then \( c[1, q.round] = c[1, r_k] = c_1[1, r_2 - r_1], c_2[1, r_3 - r_2] \ldots c_{k-1}[1, r_k - r_{k-1}] \). We take for \( i \in [1, k - 1] : q_i \) the state such that \( q_i.round = r_i + 1 - r_i \) and \( \forall r > 0 : \)

    \[
    \left( \begin{array}{c}
    q_i(r) = c_i(r, p) \\
    q_i(r) = q(r + \sum_{j \in [1,k-1]} q_i.round) \quad \text{if } r \leq q_i.round \\
    q_i(r) = q(r + \sum_{j \in [1,k-2]} q_i.round)
    \end{array} \right) \quad \text{otherwise}
    \]

    First, \( f \) is valid for \( \text{DEL} \) by Lemma 7.2 and Definition 7.3. Then by validity of \( f \) and by application of Lemma 7.2, for \( i \in [1, k - 1] \) we have \( q_i \in f \). We see that \( \forall r > 0 : q(r) = (q_1 \leadsto \cdots \leadsto q_{k-1})(r) \). Indeed, \( \forall r \in [r_i + 1, r_i + 1] : q(r) = c(r, p) = c_i(r - r_i, p) = q_k - q_k - (r - \sum_{j \in [1,k-2]} q_j.round) = (q_1 \leadsto \cdots \leadsto q_{k-1})(r) \); and

    - If \( q.round > r_k \), we can apply the same reasoning as in the previous case, the only difference being \( c[1, q.round] = c_1[1, r_2 - r_1], c_2[1, r_3 - r_2] \ldots c_{k-1}[1, r_k - r_{k-1}], c_k[1, q.round - r_k] \).

- \( (\subseteq) \) Let \( q \in f^* \). By Definition 5.8 of operations for strategies, \( \exists q_1, q_2, \ldots, q_k \in f : q = q_1 \leadsto q_2 \leadsto \cdots \leadsto q_k \). By Definition 7.3 of the minimal conservative strategy and by minimality of \( f \) for \( \text{DEL} \), \( \exists c_1, c_2, \ldots, c_k \in \text{DEL} \), \( \exists p_1, p_2, \ldots, p_k \in \Pi : \forall i \in [1, k], q_i = \langle q_i.round, \{ (r, j) | r \leq q_i.round \land j < c_i(r, p_i) \} \rangle \). By Definition 7.7 of prefix symmetry, \( \text{DEL} \) is prefix symmetric implies that \( \forall i \in [2, k], \exists c'_i \in \text{DEL} : \forall r \leq q_i.round : c'_i(r, p_1) = c_i(r, p_1). \) For \( i = 1 \), we have \( c'_1 = c_1 \). We take \( c = c'_1[1, q_1.round], c'_2[1, q_2.round] \ldots c'_{k-1}[1, q_{k-1}.round], c'_k \), thus \( c \in c'_1 \leadsto c'_2 \leadsto \cdots \leadsto c'_k \). Then \( \forall r \leq q.round = \sum_{i \in [1,k]} q_i.round, \exists i \in [1, k] \) such
that \( r \in \left[ \sum_{t \in [1,i-1]} q_t.\text{round} + 1, \sum_{t \in [1,i]} q_t.\text{round} \right] \), and \( q(r) = q_i(r - \sum_{t \in [1,i-1]} q_t.\text{round}) = c_i(r - \sum_{t \in [1,i-1]} q_t.\text{round}, p_i) = c'_i(r - \sum_{t \in [1,i-1]} q_t.\text{round}, p_1) = c(r, p_1). \)

We have found \( c \) and \( p \) showing that \( q \) is in the minimal conservative strategy for \( \text{DEL}^\omega \) by Definition 7.3. \( \square \)

7.3. Computing Heard-Of Predicates of Conservative Strategies. The analogy with oblivious strategies breaks here: the heard-of predicate of conservative strategies is hard to compute, as it depends in intricate ways on the delivered predicate itself. Yet it is still possible to compute interesting information on this HO: upper bounds. These are overapproximations of the actual HO, but they can serve for formal verification of LTL properties. Indeed, the executions of an algorithm for the actual HO are contained in the executions of the algorithm for any overapproximation of the HO, and LTL properties must be true for all executions of the algorithm. So proving the property on an overapproximation also proves it on the actual HO.

**Theorem 7.11** (Upper Bounds on HO of Minimal Conservative Strategies). Let \( \text{DEL}, \text{DEL}_1, \) and \( \text{DEL}_2 \) be delivered predicates containing \( c_{\text{total}} \).

Let \( f_1^{\text{cons}}, f_2^{\text{cons}} \) be their respective minimal conservative strategies, and \( f_1^{\text{obliv}}, f_2^{\text{obliv}} \) be their respective minimal oblivious strategies. Then:

- \( \text{HO}^{f_1^{\text{cons}}} \cap f_2^{\text{cons}}(\text{DEL}_1 \cup \text{DEL}_2) \subseteq \text{HOProd}(\text{Nexts}_{f_1^{\text{obliv}}} \cup \text{Nexts}_{f_2^{\text{obliv}}}) \).
- \( \text{HO}^{f_1^{\text{cons}}} \cup f_2^{\text{cons}}(\text{DEL}_1 \nRightarrow \text{DEL}_2) \subseteq \text{HOProd}(\text{Nexts}_{f_1^{\text{obliv}}} \cup \text{Nexts}_{f_2^{\text{obliv}}}) \).
- \( \text{HO}^{f_1^{\text{cons}}} \cap f_2^{\text{cons}}(\text{DEL}_1 \otimes \text{DEL}_2) \subseteq \text{HOProd}(\{n_1 \cap n_2 | n_1 \in \text{Nexts}_{f_1^{\text{obliv}}} \land n_2 \in \text{Nexts}_{f_2^{\text{obliv}}} \}) \).
- \( \text{HO}^{f_1^{\text{cons}}} \cap \text{DEL}^\omega \subseteq \text{HOProd}(\text{Nexts}_{f_1^{\text{obliv}}}) \).

**Proof.** An oblivious strategy is a conservative strategy. Therefore, the minimal conservative strategy always dominates the minimal oblivious strategy. Hence we get an upper bound on the heard-of predicate of the minimal conservative strategies by applying Theorem 6.11. \( \square \)

7.4. Domination by Conservative Strategies. Some examples above, like \( \text{DEL}_{i,\geq r}^{\text{crash}} \) (see Table 1), are not dominated by oblivious strategies, but are dominated by conservative strategies. This follows from a condition on delivered predicates and its invariance by the operations, similar to the case of oblivious strategies. Let’s start by defining that condition and then showing that it implies domination by a conservative strategy.

**Definition 7.12** (Common Prefix Property). Let \( \text{DEL} \) be a delivered predicate. \( \text{DEL} \) satisfies the **common prefix property** \( \Rightarrow \forall c \in \text{DEL}, \forall p \in \Pi, \forall r > 0, \exists c' \in \text{DEL}, \forall q \in \Pi, \forall r' \leq r : c'(r', q) = c(r', p) \).

The common prefix property, as its name suggests, works just like the common round property but for a prefix. It ensures that for every prefix of a collection in the predicate, there exists a collection where every process shares this prefix.

**Theorem 7.13** (Sufficient Condition of Conservative Domination). Let \( \text{DEL} \) be a delivered predicate satisfying the common prefix property Then, there is a conservative strategy that dominates \( \text{DEL} \).
Proof. The proof is the same as for the oblivious case, except that the common prefix property gives us a delivered collection where everyone has the same exact prefix as the blocked process in the canonical execution.

\[\square\]

**Theorem 7.14** (Dominance by Conservative for Operations). Let \( \text{DEL}_1, \text{DEL}_2, \text{DEL}_3 \) be delivered predicates with the common prefix property. Then \( \text{DEL}_1 \cup \text{DEL}_2, \text{DEL}_1 \otimes \text{DEL}_2, \text{DEL}_1 \leadsto \text{DEL}_2, \text{DEL}_3 \) satisfy the common prefix property.

Proof.

- Let \( c \in \text{DEL}_1 \cup \text{DEL}_2 \). Thus \( c \in \text{DEL}_1 \) or \( c \in \text{DEL}_2 \) by Definition 4.1. We fix \( c \in \text{DEL}_1 \) (the other case is symmetric). Then for \( p \in \Pi \) and \( r > 0 \), we get a \( c' \in \text{DEL}_1 \) satisfying the condition of Definition 7.12. Since \( \text{DEL}_1 \subseteq \text{DEL}_1 \cup \text{DEL}_2 \), we get \( c' \in \text{DEL}_1 \cup \text{DEL}_2 \). We conclude that the common prefix property still holds for \( \text{DEL}_1 \cup \text{DEL}_2 \) by Definition 7.12.

- Let \( c \in \text{DEL}_1 \otimes \text{DEL}_2 \). Then \( \exists c_1 \in \text{DEL}_1, \exists c_2 \in \text{DEL}_2 : c = c_1 \otimes c_2 \). For \( p \in \Pi \) and \( r > 0 \), our hypothesis on \( \text{DEL}_1 \) and \( \text{DEL}_2 \) ensures that there are \( c_1' \in \text{DEL}_1 \) satisfying the condition of Definition 7.12 for \( c_1 \) and \( c_2' \in \text{DEL}_2 \) satisfying the condition of Definition 7.12 for \( c_2 \). We argue that \( c' = c_1' \otimes c_2' \) satisfies the condition of Definition 7.12 for \( c \). Indeed, \( \forall r, \forall q \in \Pi : c(r, q) = c_1'(r, q) \otimes c_2'(r, q) = c_1(r_1, p) \otimes c_2(r, p) = c(r, p) \). We conclude that the condition of Definition 7.12 still holds for \( \text{DEL}_1 \otimes \text{DEL}_2 \).

- Let \( c \in \text{DEL}_1 \leadsto \text{DEL}_2 \). Since \( c \in \text{DEL}_2 \), the condition holds by hypothesis, we study the case where succession actually happens. Hence \( \exists c_1, c_2 \in \text{DEL}_2, \exists_{\text{change}} > 0 : c = c_1[1, r_{\text{change}}], c_2 \). For \( p \in \Pi \) and \( r > 0 \), our hypothesis on \( \text{DEL}_1 \) and \( \text{DEL}_2 \) ensures that there are \( c_1' \in \text{DEL}_1 \) satisfying the condition for \( c_1 \) at \( r \) and \( c_2' \in \text{DEL}_2 \) satisfying the condition for \( c_2 \) at \( r - r_{\text{change}} \). We argue that \( c' = c_1'[1, r_{\text{change}}], c_2' \) satisfies the condition for \( c \). Indeed, \( \forall r, \forall q \in \Pi \), we have: if \( r' \leq r_{\text{change}} : c'(r, q) = c_1'(r', q) = c_1(r_1, p) = c(r, p) \); and if \( r' > r_{\text{change}} : c'(r, q) = c_2'(r' - r_{\text{change}}, q) = c_2(c_2'(r', p)) = c(r, p) \). We conclude that the condition still holds for \( \text{DEL}_1 \leadsto \text{DEL}_2 \).

- Let \( c \in \text{DEL}_3, p \in \Pi, r > 0 \) and let’s prove that \( \exists c' \in \text{DEL}_3, \forall q \in \Pi, \forall r' \leq r : c'(r', q) = c(r', p) \). Let \( \exists c_1', c_2' \in \text{DEL}_3, \forall q \in \Pi : c(r', p) = c_1'(r, q) \otimes c_2'(r, q) = c_1(r_1, p) \otimes c_2(r, p) \). We conclude that the condition of Definition 7.12 still holds for \( \text{DEL}_3 \).

Therefore, as long as the initial building blocks satisfy the common prefix property, so do the results of the operations. Thus the latter is dominated by its minimal conservative strategy — a strategy that can be computed from the results of this section.

### 8. Looking at Future Rounds

In the above, the dominating strategy was at most conservative: only the past and present rounds were useful for generating heard-of collections. Nevertheless, messages from future rounds serve in some cases. This section provides a preliminary exploration of the topic, with an example and a conjecture.

Let’s go back to \( \text{DEL}_2 \), the delivered predicate for at most one message loss presented in Section 6. The minimal oblivious strategy for this predicate is \( f_{n-1} \). The minimal
A conservative strategy is a similar one, except that when it received a message from $p$ at round $r$, it waits for all messages from $p$ at previous rounds. However, this does not change which messages the strategy waits for in the current round: $n - 1$ messages, because one can always deliver all the messages from the past, and then the loss might be a message from the current round. However, if the strategy considers messages from the next round, it can ensure that at each round, at most one message among all processes is not delivered on time. The strategy presented here waits for either all messages from the current round, or for all but one message from the current round and all but one message from the next round.

**Definition 8.1 (Strategy for One Loss).** Let $after : Q \rightarrow P(Π)$ such that $∀q ∈ Q : after(q) = \{k ∈ Π | \langle q.round + 1, k \rangle ∈ q.mes \}$. Then $f_{loss} ≜ \bigcup_{c ∈ f_{loss}} \{q ∈ Q \mid \begin{array}{l} \text{card}(obliv(q)) = \text{card}(Π) \\
\text{or} \ (\text{card}(after(q)) = \text{card}(Π) - 1 \land \text{card}(obliv(q)) = \text{card}(Π) - 1) \end{array} \}

Intuitively, this strategy is valid for $\text{DEL}^{loss}_1$ because at each round and for each process, only two cases exist:

- Either no message for this process at this round is lost, and it receives a message from every process;
- Or one message for this process is lost at this round, and it only receives $n - 1$ messages. However, all the other processes receive $n$ messages (because only one can be lost), thus they change round and send their messages for the next round. Since the one loss already happened, all these messages are delivered, and the original process eventually receives $n - 1$ messages from the next round.

**Lemma 8.2 (Validity of $f_{loss}$).** $f_{loss}$ is valid for $\text{DEL}^{loss}_1$.

**Proof.** We proceed by contradiction: Assume $f_{loss}$ is invalid for $\text{DEL}^{loss}_1$. Thus there exists $t ∈ \text{execs}_{f_{loss}}(\text{DEL}^{loss}_1)$ invalid. There is a smallest round $r$ where some process $j$ cannot change round from that point onwards. Let also $c$ be a delivered collection of $\text{DEL}^{loss}_1$ such that $t ∈ \text{execs}(c)$. Minimality of $r$ entails that every process reaches round $r$ and thus sends its messages to $j$, and $c ∈ \text{DEL}^{loss}_1$ entails that at most one of these messages can be lost. Thus $j$ eventually receives $n - 1$ messages from round $r$. By hypothesis, it doesn’t receive all $n$ messages, or it could change round. Thus $j$ receives exactly $n - 1$ messages from round $r$, which means that the only loss allowed by $\text{DEL}^{loss}_1$ happens at round $r$. For $j$ to block, it must never receive $n - 1$ messages from round $r + 1$. Yet the only loss is a message to $j$; thus every other process receives $n$ messages at round $r$, changes round, and sends its message to $j$ without loss. Hence $j$ eventually receives $n - 1$ messages from round $r + 1$. This contradicts the fact that $j$ cannot change round at this point in $t$.

This strategy also ensures that at most one process per round receives only $n - 1$ messages on time — the others must receive all the messages. This vindicates the value of messages from future rounds for some delivered predicates, such as the ones with asymmetry in them.

**Theorem 8.3 (Heard-Of Characterization of $f_{loss}$).**

$\text{HO}_{f_{loss}}(\text{DEL}^{loss}_1) = \{h, \text{ a heard-of collection} | ∀r > 0, \sum_{p ∈ Π} \text{card}(Π \left\{ p \mid ho(r, p) \right\}) ≤ 1\}$.

**Proof.**

- ($⊆$) Let $ho ∈ \text{HO}_{f_{loss}}(\text{DEL}^{loss}_1)$ and $t ∈ \text{execs}_{f_{loss}}(\text{DEL}^{loss}_1)$ an execution of $f_{loss}$ generating $ho$. By definition of the executions of $f_{loss}$, processes change round only when they received
either $n$ messages from the current round, or $n - 1$ messages from the current round (and $n - 1$ messages from the next one, but that is irrelevant to the heard-of predicate). Moreover, $t$ is valid by definition, as it generates $ho$. Let’s now assume that at least one process $j$ receives only $n - 1$ messages on time for some round $r$ in $ho$. By definition of $f_{loss}$ and validity of $t$, we deduce that $j$ also received $n - 1$ messages from round $r + 1$ while it was at round $r$. Hence, every other process ended its own round $r$ before $j$; the only possibility is that they received $n$ messages from round $r$, because the alternatives require the reception of the message from $j$ at round $r + 1$. We conclude that for each round, at most one process receives only $n - 1$ messages on time, which can be rewritten as $\forall r \in \mathbb{N}^* : \sum_{j \in \Pi} \text{card}(\Pi \setminus ho(r, j)) \leq 1$.

• $(\supseteq)$ Let $ho$ a heard-of collection over $\Pi$ such that $\forall r \in \mathbb{N}^* : \sum_{j \in \Pi} \text{card}(\Pi \setminus ho(r, j)) \geq 1$. The difficulty here is that the canonical execution of $ho$ fails to be an execution of $f_{loss}$: when only $n - 1$ messages from the current round are delivered to some process $j$, then the corresponding $next_j$ for this round will not be allowed by $f_{loss}$. One way to deal with this issue is to start from the canonical execution of $ho$ and move these incriminating $next_j$ after the deliveries of $n - 1$ messages from the next round, and before the deliveries of messages from $j$ in the next round. In this way, every $next_j$ will happen when either $n$ messages have been received from the current round, or $n - 1$ messages from the current round and $n - 1$ from the next one. We conclude that $ho \in HO_{f_{loss}}(DEL_{loss}^1)$.

Does $f_{loss}$ dominate $DEL_{loss}^1$? It would seem so, but proving it is harder than for $f_{n-F}$ and $DEL_{crash}^F$. The reason is that the common round property of the latter allows the creation of deadlocks where every process is blocked in the same local state, which forces any valid strategy to accept this state. Whereas the whole reason the future serves in $DEL_{loss}^1$ is because the latter doesn’t have this property, and thus the local state of a process constrains the possible local states of other processes.

**Conjecture 8.4** (Domination of $f_{loss}$ on $DEL_{loss}^1$). $f_{loss}$ is a dominating strategy for $DEL_{loss}^1$.

This example demonstrates two important points about strategies using the future. First, for some delivered predicates (for example $DEL_{loss}^1$), they dominate conservative strategies. Secondly, because any additional message might influence whether the strategy allows a change of round or not, proof techniques based on standard executions don’t work for these strategies.

9. **Conclusion**

In this article, we propose a formalization of the heard-of predicate to use when studying a given operational model through the Heard-Of model. This formalization comes with the following methodology:

• Extract a delivered predicate from the informal model, either through direct analysis or by building the predicate from simpler building blocks through operations.
• Compute a dominating strategy for this delivered predicate, either by direct analysis or by combining dominating strategies for the simpler building blocks.
• Compute the heard-of predicate generated by this strategy on this delivered predicate.

This result captures the most constrained predicate which can be implemented on top of the initial model. If a round-based algorithm is proved correct on this predicate, its correctness
follows on the original model; and if no algorithm exists for a given problem on this predicate, this entails that no round-based algorithm solves the problem on the original model.

The obvious follow-up to this research is to tackle strategies which look into the future, and predicates like $\text{DEL}_1^{\text{loss}}$ that are useful for such strategies. Doing so will require completely new proof techniques, as the ones presented here implicitly rely on the ability to make only the messages in the past and present rounds matter. A more straightforward extension of this work would be the study of more delivered predicates, both for having more building blocks to use with operations, and to derive more heard-of predicates.

**Acknowledgement.** This work was supported by project PARDI ANR–16–CE25–0006. The content of this article was partially published in *Characterizing Asynchronous Message-Passing Models Through Rounds* [21] published at OPODIS 2018, and *Derivation of Heard-Of Predicates From Elementary Behavioral Patterns* [22] published at FORTE 2020.

**References**


Lemma A.1 (Lemma 5.12 Correctness of Standard Execution). Let $c$ be a delivered collection and $f$ be a strategy. Then $st(f, c) \in \text{exec}_f(c)$.

Proof idea. First, the proof shows that $st(f, c)$ is indeed an execution by verifying the three properties of Definition 5.1. Then, it shows that $st(f, c)$ is an execution of the delivered collection $c$ (Definition 5.2: the delivered messages in $st(f, c)$ are exactly those from $c$). Lastly the verification of the two conditions of Definition 5.6 ensures that $st(f, c)$ is an execution of strategy $f$.

Proof. Let us first show that $st(f, c)$ is an execution by showing each point of Definition 5.1.

- Delivered after sending: By Definition 5.11 of the standard execution there are $r - 1$ transitions $\text{next}_p$ before the messages of $p$ sent at round $r$ are delivered.

- Delivered only once: If a message sent at round $r$ by $p$ is delivered, we know from the previous point that $p$ reaches round $r$ before the delivery. Let $r'$ be such that $\text{changes}_{r'}$ contains the $(r - 1)^{\text{th}} \text{next}_p$ of $st(f, c)$. Then the message is delivered in $\text{dels}_{r'+1}$ by Definition 5.11 of the standard execution. For all $r'' > r' + 1$, if there are deliveries from $p$ in $\text{dels}_{r''}$, this entails that $\text{next}_p \in \text{changes}_{r''-1}$, and thus that $p$ is not anymore at round $r$. By definition of $\text{dels}_{r''}$, it only delivers messages sent at the current rounds of processes. We conclude that there is only one delivery of the message.

- Once stopped, forever stopped: By Definition 5.11 of the standard execution, if $\text{changes}_r$ contains only $\text{stop}$, this means that $f$ does not allow any process to change rounds with the currently received messages. By definition of $\text{dels}_r$, it only delivers messages from processes that changed round in $\text{changes}_{r-1}$. If there is some smallest $r_{\text{stop}}$ such that $\text{changes}_{r_{\text{stop}}} = \{\text{stop}\}$, then $\text{dels}_{r_{\text{stop}}+1} = \emptyset$. This means the local states of processes do not change, and thus $\text{changes}_{r_{\text{stop}}+1} = \{\text{stop}\}$. By induction, if there is some $\text{stop}$ in $st(f, c)$, the rest of the execution contains only $\text{stop}$ transitions.

Hence $st(f, c)$ is an execution. Next, let’s show that $st(f, c)$ is an execution of $c$. By Definition 5.2, this means the delivered messages are exactly those from $c$, for processes that reached the round where they send the message. By Definition 5.11 of the standard execution, all deliveries are from messages in $c$. By Definition 5.11 of the standard execution,
if \( p \) reaches round \( r \), there is a smallest \( r' > 0 \) such that \( \text{round}_p^{r'} = r \). This means that \( \text{dels}_{r'} \) contains the deliveries of all the messages \( (r, p, q) \) such that \( p \in c(r, q) \). Hence \( st(f, c) \) is an execution of \( c \). Finally, we show that \( st(f, c) \) is an execution of \( f \). We check the two conditions of Definition 5.6:

- (All Nexts Allowed) By Definition 5.11 of the standard executions, changes of round only occur when the local state is in \( f \).
- (Fairness) If some process is blocked forever at some round, this means by Definition 5.11 of the standard execution that its local state was not in \( f \) for an infinite number of \( \text{changes}_r \), and so for an infinite number of times.

We conclude that \( st(f, c) \in \text{execs}_f(c) \). \( \square \)